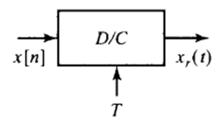
• Notes:

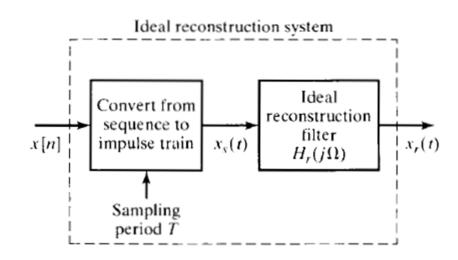
- Discrete-time frequency
 - Normalized
 - Radian
 - Maximum frequency
- Continuous-time frequency
 - Radian/sec or Hz

- Remark on D/C:
 - Remember that



$$x_r(t) = \sum_{n=-\infty}^{\infty} x[n]h_r(t-nT).$$

$$x_r(t) = \sum_{n=-\infty}^{\infty} x[n] \frac{\sin[\pi(t-nT)/T]}{\pi(t-nT)/T}$$



Therefore, CTFT of both of

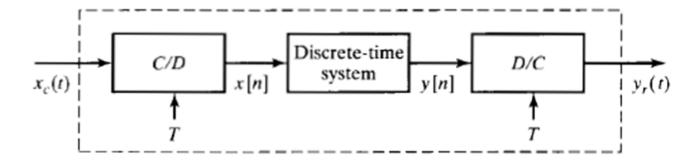
$$x_r(t) = \sum_{n=-\infty}^{\infty} x[n]h_r(t-nT).$$

- Gives
$$X_r(j\Omega) = \sum_{n=-\infty}^{\infty} x[n]H_r(j\Omega)e^{-j\Omega Tn}$$

Now, observe that

$$X_r(j\Omega) = H_r(j\Omega)X(e^{j\Omega T})$$

 Discrete-time processing of the continuoustime signals



We know that

$$x[n] = x_c(nT).$$

and the relationship between FT

$$X(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_{c} \left(j \left(\frac{\omega}{T} - \frac{2\pi k}{T} \right) \right)$$

and from reconstruction (interpolation)

$$y_r(t) = \sum_{n=-\infty}^{\infty} y[n] \frac{\sin[\pi(t-nT)/T]}{\pi(t-nT)/T},$$

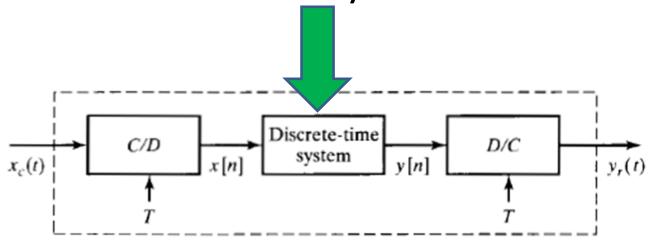
 Hence, for the DT processing of CT signals we have (see ideal D/C):

$$Y_r(j\Omega) = H_r(j\Omega)Y(e^{j\Omega T})$$

$$= \begin{cases} TY(e^{j\Omega T}), & |\Omega| < \pi/T, \\ 0, & \text{otherwise.} \end{cases}$$

- Special case: the identity system $y[n] = x[n] = x_c(nT)$
 - then $y_r(t) = x_c(t)$

• We consider an DT LTI system:



$$Y(e^{j\omega}) = H(e^{j\omega})X(e^{j\omega})$$

$$Y_r(j\Omega) = H_r(j\Omega)H(e^{j\Omega T})X(e^{j\Omega T})$$

We had

$$X(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c \left(j \left(\frac{\omega}{T} - \frac{2\pi k}{T} \right) \right)$$

— Which results in ($\omega = \Omega T$)

$$Y_r(j\Omega) = H_r(j\Omega)H(e^{j\Omega T})\frac{1}{T}\sum_{k=-\infty}^{\infty}X_c\left(j\left(\Omega - \frac{2\pi k}{T}\right)\right)$$

• Double check sampling frequency....

Reasonably

$$X_c(j\Omega) = 0$$
 for $|\Omega| \ge \pi/T$.

Therefore

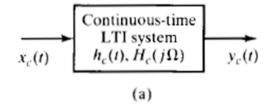
$$Y_r(j\Omega) = \begin{cases} H(e^{j\Omega T})X_c(j\Omega), & |\Omega| < \pi/T, \\ 0, & |\Omega| \ge \pi/T. \end{cases}$$

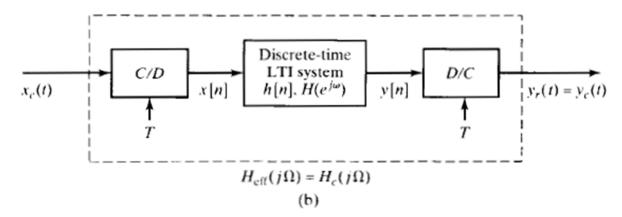
Finally

$$Y_r(j\Omega) = H_{\text{eff}}(j\Omega)X_c(j\Omega),$$

$$H_{\text{eff}}(j\Omega) = \begin{cases} H(e^{j\Omega T}), & |\Omega| < \pi/T, \\ 0, & |\Omega| \ge \pi/T. \end{cases}$$

Detailed diagram



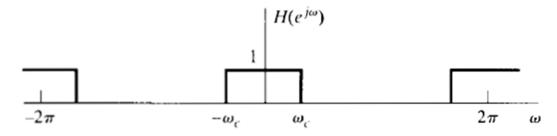


(a) Continuous-time LTI system.
 (b) Equivalent system for bandlimited inputs.

- Note: important assumptions
 - An LTI DT system
 - Band-limited input signal $x_c(t)$
 - Sampling rate above the Nyquest rate
- Then the diagram can be modeled via a CT LTI system

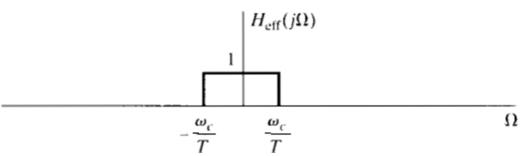
Example: ideal LPF

$$H(e^{j\omega}) = \begin{cases} 1, & |\omega| < \omega_c, \\ 0, & \omega_c < |\omega| \le \pi. \end{cases}$$

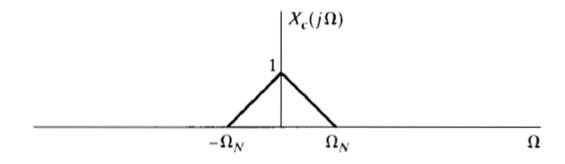


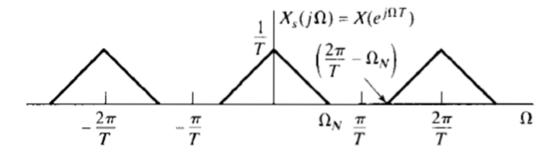
Then,

$$H_{\text{eff}}(j\Omega) = \begin{cases} 1, & |\Omega T| < \omega_{\epsilon} \text{ or } |\Omega| < \omega_{\epsilon}/T, \\ 0, & |\Omega T| > \omega_{\epsilon} \text{ or } |\Omega| > \omega_{\epsilon}/T. \end{cases}$$

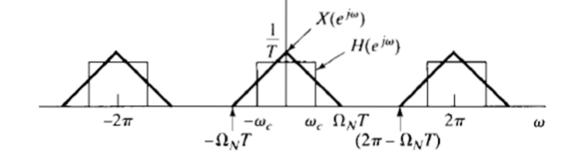


LPF of CT signals via DT ideal LPF

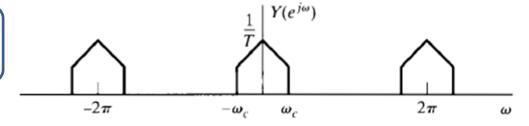


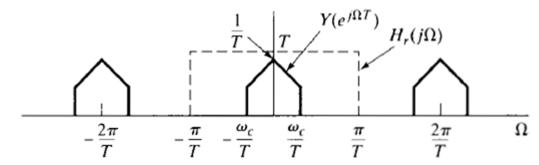


• And,

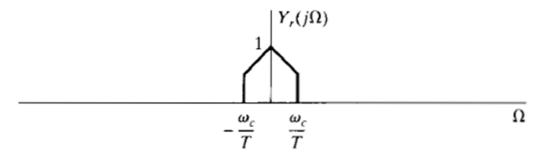


$$(2\pi - \Omega_N T) > \Omega_N T.$$





Finally, the output is given by

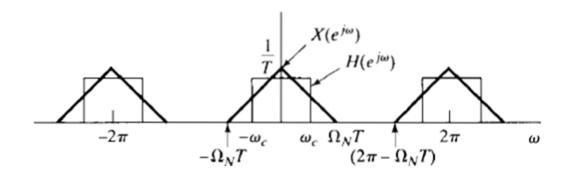


- Observation: cut-off frequency of the CT LPF
 - Sampling frequency
 - DT cut-off frequency

Example: select sampling period such that

$$\Omega_N T < \omega_c$$

- Herein, $y_r(t) = x_c(t)$



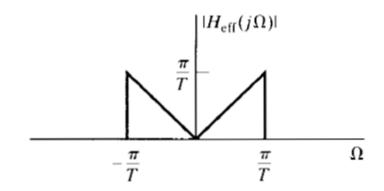
- Example: differentiator
 - We know that

$$y_c(t) = \frac{d}{dt}[x_c(t)].$$

$$H_c(j\Omega) = j\Omega$$

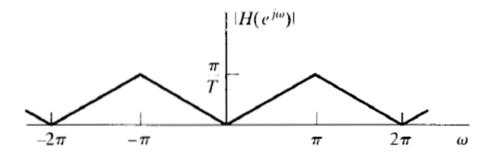
Also,

$$H_{\mathrm{eff}}(j\Omega) = \begin{cases} j\Omega, & |\Omega| < \pi/T, \\ 0, & |\Omega| \ge \pi/T, \end{cases}$$



The corresponding DT system

$$H(e^{j\omega}) = \frac{j\omega}{T}, \qquad |\omega| < \pi,$$



With the impulse response

$$h[n] = \frac{\pi n \cos \pi n - \sin \pi n}{\pi n^2 T}, \quad -\infty < n < \infty,$$

- Or

$$h[n] = \begin{cases} 0, & n = 0, \\ \frac{\cos \pi n}{nT}, & n \neq 0. \end{cases}$$

— And the implementation of CT differentiator is done in CT domain!

• Example: differentiation of sin

$$x_c(t) = \cos(\Omega_0 t)$$

$$\Omega_0 < \pi/T.$$

$$x[n] = \cos(\omega_0 n)$$

$$\omega_0 = \Omega_0 T < \pi$$

$$X(e^{j\Omega T}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} [\pi \delta(\Omega - \Omega_0 - k \Omega_s) + \pi \delta(\Omega + \Omega_0 - k \Omega_s)].$$

And for the baseband,

$$X(e^{j\Omega T}) = \frac{\pi}{T}\delta(\Omega - \Omega_0) + \frac{\pi}{T}\delta(\Omega + \Omega_0)$$
 for $|\Omega| \le \pi/T$.

- Using $\Omega = \omega/T$

$$X(e^{j\omega}) = \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0), \qquad |\omega| \le \pi.$$

• Prove that $\delta(\omega/T) = T\delta(\omega)$.

- Always remember that
- $X(e^{j\omega})$ is repeated with period 2π
- $X(e^{j\Omega T})$ is repeated with period $2\pi/T$.
- Straightforwardly:

$$Y(e^{j\omega}) = H(e^{j\omega})X(e^{j\omega})$$

$$= \frac{j\omega}{T} [\pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)]$$

$$= \frac{j\omega_0\pi}{T} \delta(\omega - \omega_0) - \frac{j\omega_0\pi}{T} \delta(\omega + \omega_0), \quad |\omega| \le \pi.$$

And,

$$Y_r(j\Omega) = H_r(j\Omega)Y(e^{j\Omega T}) = TY(e^{j\Omega T})$$

$$= T\left[\frac{j\omega_0\pi}{T}\delta(\Omega T - \Omega_0 T) - \frac{j\omega_0\pi}{T}\delta(\Omega T + \Omega_0 T)\right]$$

$$= T\left[\frac{j\omega_0\pi}{T}\frac{1}{T}\delta(\Omega - \Omega_0) - \frac{j\omega_0\pi}{T}\frac{1}{T}\delta(\Omega + \Omega_0)\right]$$

$$= j\Omega_0\pi\delta(\Omega - \Omega_0) - j\Omega_0\pi\delta(\Omega + \Omega_0).$$

Which means

$$y_r(t) = j\Omega_0 \frac{1}{2} e^{j\Omega_0 t} - j\Omega_0 \frac{1}{2} e^{-j\Omega_0 t} = -\Omega_0 \sin(\Omega_0 t) = \frac{d}{dt} \left[x_c(t) \right]$$

- Impulse invariance
- Sampling of the impulse response of LTI CT systems

$$h[n] = Th_c(nT),$$
 $H(e^{j\omega}) = H_c\left(j\frac{\omega}{T}\right), \qquad |\omega| \le \pi.$

Example: LPF

$$H_{\mathcal{C}}(j\Omega) = \begin{cases} 1, & |\Omega| < \Omega_{\mathcal{C}}, \\ 0, & |\Omega| \leq \Omega_{\mathcal{C}}. \end{cases}$$

$$\Omega_{c} = \omega_{c}/T < \pi/T$$

The impulse response of the CT LPF:

$$h_c(t) = \frac{\sin(\Omega_c t)}{\pi t}$$

The impulse response of DT system

$$h[n] = Th_c(nT) = T\frac{\sin(\Omega_c nT)}{\pi nT} = \frac{\sin(\omega_c n)}{\pi n}$$

And,

$$\omega_c = \Omega_c T$$

$$H(e^{j\omega}) = \begin{cases} 1, & |\omega| < \omega_{c}, \\ 0, & \omega_{c} < |\omega| \le \pi. \end{cases}$$

Anti-aliasing filter