



# Numerical Integration

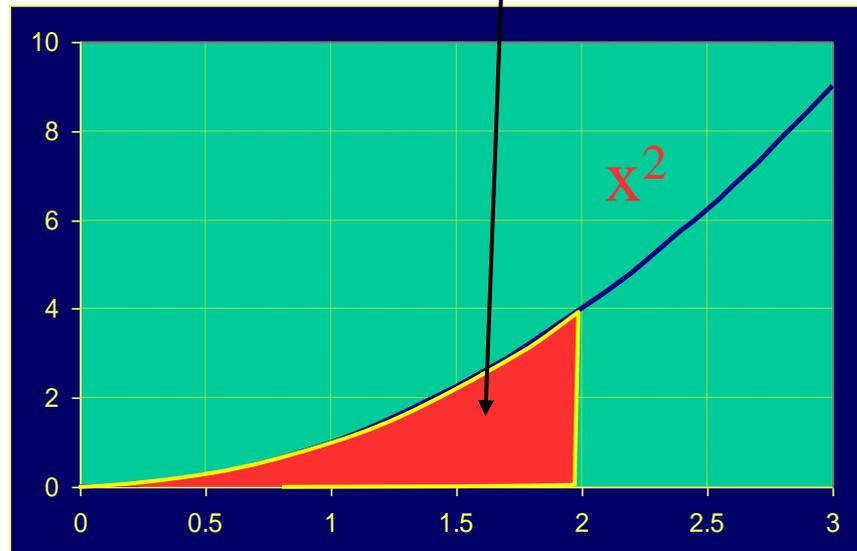
## Integrals

Indefinite

$$\int x^2 dx = \frac{1}{3}x^3 + C$$

Definite

$$\int_0^2 x^2 dx = \frac{8}{3}$$



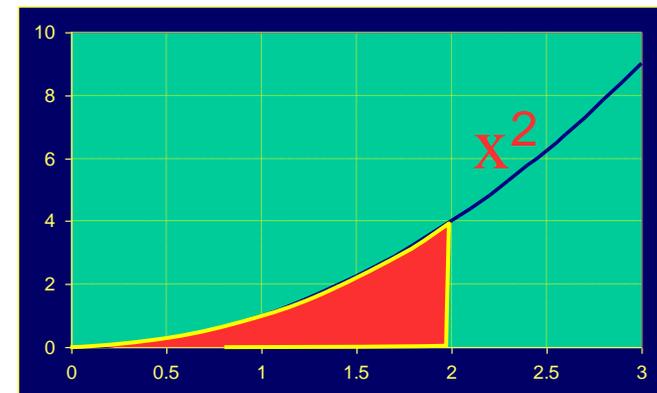
# Numerical Integration

- Can be solved exactly, but for various reasons FEA prefers to evaluate integrals like this approximately:
  - Historically, considered more efficient and reduced coding errors.
  - Only possible approach for isoparametric elements.
  - Can actually improve performance in certain cases!
- Definite integrals can be computed numerically

$$\int_a^b f(x)dx \cong \sum_i w_i f(x_i)$$

➤ Objective:

- Determine points  $x_i$
- Determine coefficients  $w_i$





# Numerical Integration

- Depending on choice of  $w_i$  and  $x_i$ 
  - Midpoint Rule
  - Trapezoidal Rule
  - Simpson's
  - Gaussian Quadratures
  - etc



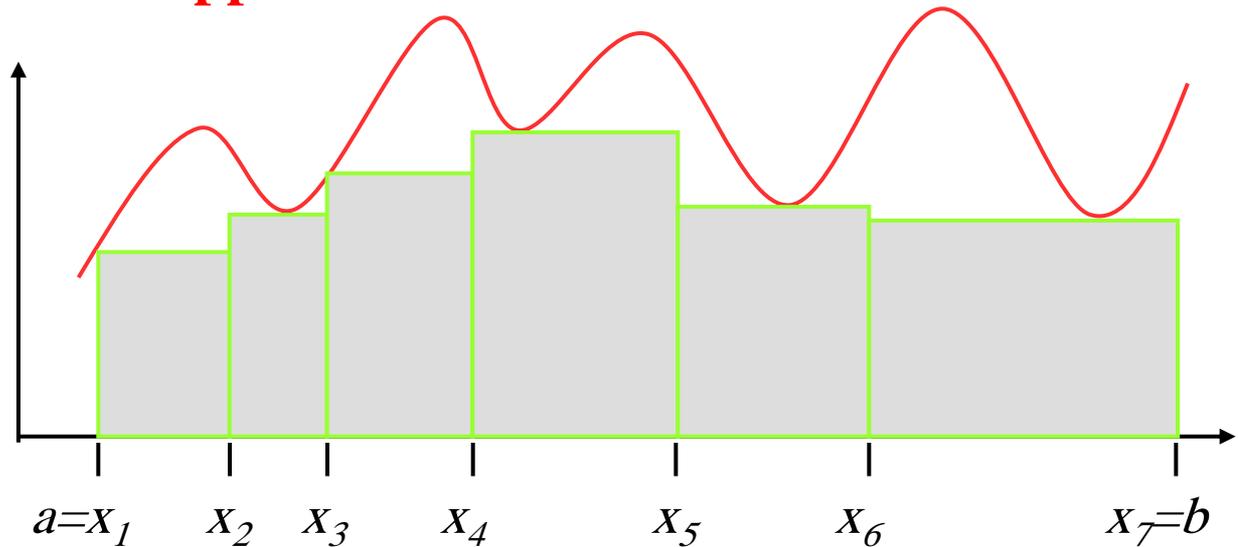
# Numerical Integration

## Numerical Integration – Upper & Lower Bounds

Depending on choice of  $w_i$  and  $x_i$

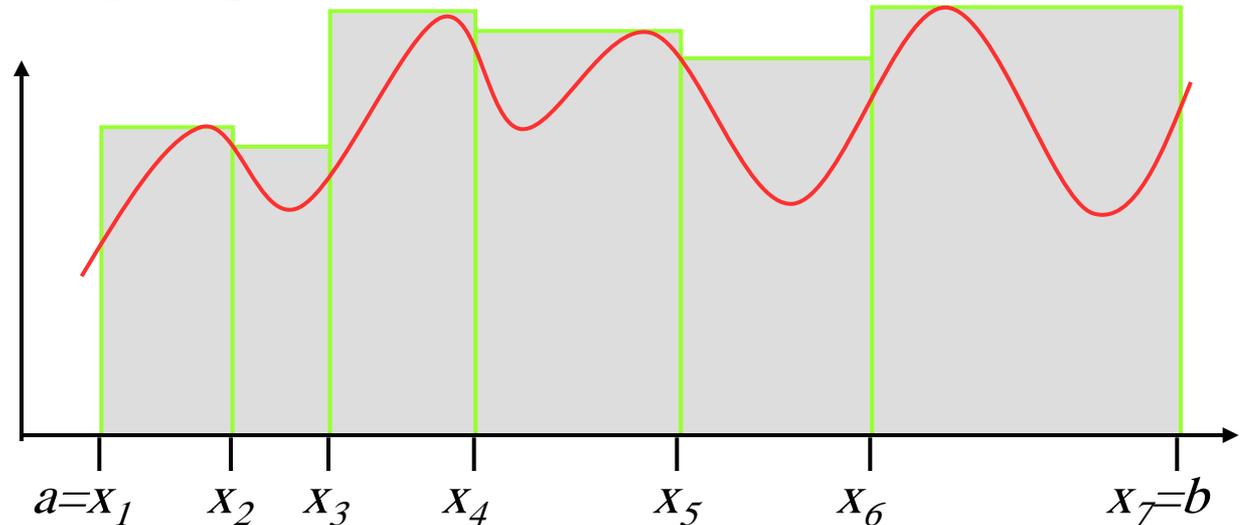
Lower Sum

$$L(f; x_i)$$



Upper Sum

$$U(f; x_i)$$





# Numerical Integration

It can be shown that

$$L(f; x_i) \leq \int_a^b f(x) dx \cong \sum_i w_i f(x_i) \leq U(f; x_i)$$

$$\lim_{i \rightarrow \infty} L(f; x_i) = \int_a^b f(x) dx = \sum_i w_i f(x_i) = \lim_{i \rightarrow \infty} U(f; x_i)$$

**Objective**

$$\int_a^b f(x) dx \cong \sum_i w_i f(x_i) = w_1 f(x_1) + w_2 f(x_2) + \dots + w_n f(x_n)$$

Where do such formulae come from?

Theory of Interpolation....

Let  $f(x) \approx p(x) = \sum_{i=1}^n l_i(x) f(x_i)$   $l_i(x)$ : cardinal functions

Recall Shape Functions



# Numerical Integration: Quadratures

$$\int_a^b f(x)dx \approx \int_a^b p(x)dx = \sum_{i=1}^n f(x_i) \int_a^b l_i(x)dx = \sum_{i=1}^n f(x_i)w_i$$

It will give correct values for the integral of every polynomial of degree  $\leq n-1$

## Gaussian Quadrature:

Karl Friedriech Gauss discovered that by a special placement of nodes the accuracy of the numerical integration could be greatly increased



# Numerical Integration: Gaussian Quadrature

Theorem on Gaussian nodes

Let  $q$  be a polynomial of degree  $n$  such that

$$\int_a^b q(x) x^k dx = 0 \quad k = 0, 1, \dots, n-1$$

Let  $x_1, x_2, \dots, x_n$  be the roots of  $q(x)$ . Then

$$\int_a^b f(x) dx \cong \sum_i w_i f(x_i) = w_1 f(x_1) + w_2 f(x_2) + \dots + w_n f(x_n)$$

with  $x_j$ 's as nodes is exact for all polynomials of degree  $\leq 2n-1$ .



# Numerical Integration: Gaussian Quadrature

Assume two point formulation, then:

$$\int_{-1}^1 F(\xi) d\xi = w_1 F(\xi_1) + w_2 F(\xi_2)$$

Four equations are created using Legendre polynomials  $(1, \xi, \xi^2, \xi^3)$

$$w_1 F(\xi_1) + w_2 F(\xi_2) = \int_{-1}^1 1 d\xi = 2$$

$$w_1 F(\xi_1) + w_2 F(\xi_2) = \int_{-1}^1 \xi d\xi = 0$$

$$w_1 F(\xi_1) + w_2 F(\xi_2) = \int_{-1}^1 \xi^2 d\xi = 2/3$$

$$w_1 F(\xi_1) + w_2 F(\xi_2) = \int_{-1}^1 \xi^3 d\xi = 0$$

$$w_1 (1) + w_2 (1) = 2$$

$$w_1 (\xi_1) + w_2 (\xi_2) = 0$$

$$w_1 (\xi_1)^2 + w_2 (\xi_2)^2 = 2/3$$

$$w_1 (\xi_1)^3 + w_2 (\xi_2)^3 = 0$$

$$w_1 = w_2 = 1$$

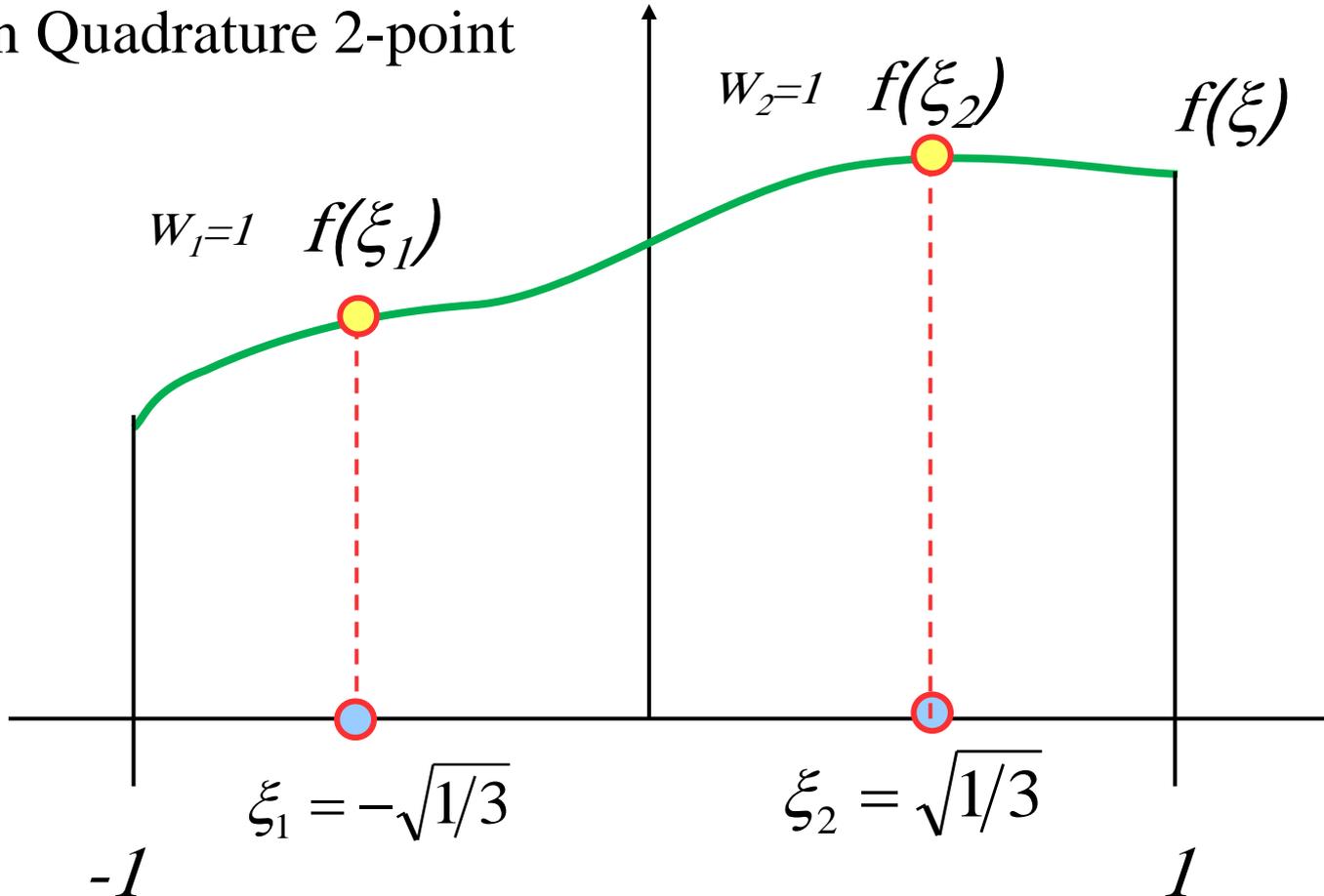
$$\xi_1 = -1/\sqrt{3}$$

$$\xi_2 = 1/\sqrt{3}$$



# Numerical Integration: Gaussian Quadrature

## Gaussian Quadrature 2-point



$$\int_{-1}^1 f(x) dx \cong 1 * f\left(-\sqrt{1/3}\right) + 1 * f\left(\sqrt{1/3}\right)$$



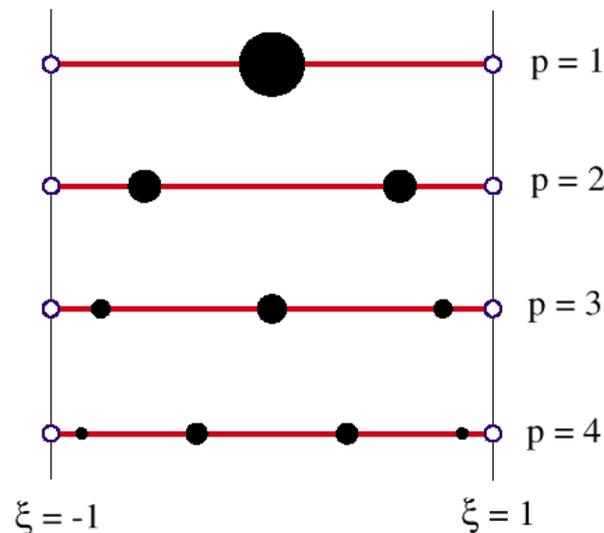
# Numerical Integration: Gaussian Quadrature

## One Dimensional Gauss Integration Rules:

One point: 
$$\int_{-1}^1 F(\xi) d\xi \doteq 2F(0),$$

Two points: 
$$\int_{-1}^1 F(\xi) d\xi \doteq F(-1/\sqrt{3}) + F(1/\sqrt{3}),$$

Three points: 
$$\int_{-1}^1 F(\xi) d\xi \doteq \frac{5}{9}F(-\sqrt{3/5}) + \frac{8}{9}F(0) + \frac{5}{9}F(\sqrt{3/5})$$





# Numerical Integration: Gaussian Quadrature

## Weighting Factors & Sampling Points for Gauss-Legendre Formula

<i>Points(n)</i>	<i>Weighting Factor (<math>w_i</math>)</i>	<i>Sampling Points (<math>\xi_i</math>)</i>
2	$w_1 = 1.00000000$	$\xi_1 = -.577350269$
	$w_2 = 1.00000000$	$\xi_2 = .577350269$
3	$w_1 = 0.55555556$	$\xi_1 = -.774596669$
	$w_2 = 0.88888889$	$\xi_2 = 0.0$
	$w_3 = 0.55555556$	$\xi_3 = 0.774596669$
4	$w_1 = 0.3478548$	$\xi_1 = -.861136312$
	$w_2 = 0.6521452$	$\xi_2 = -.339981044$
	$w_3 = 0.6521452$	$\xi_3 = 0.339981044$
	$w_4 = 0.3478548$	$\xi_4 = .861136312$
5	$w_1 = 0.2369269$	$\xi_1 = -.906179846$
	$w_2 = 0.4786287$	$\xi_2 = -.538469310$
	$w_3 = 0.5688889$	$\xi_3 = 0.0$
	$w_4 = 0.4786287$	$\xi_4 = .538469310$
	$w_5 = 0.2369269$	$\xi_5 = .906179846$



# Numerical Integration: Gaussian Quadrature

Example:

$$I = \int_2^6 (x^2 + 5x + 3)dx = ? \quad \text{Analytical solution} \rightarrow 161.3333$$

$$x = 4 + 2\xi \quad \rightarrow \quad I = \int_{-1}^1 \underbrace{2[(4 + 2\xi)^2 + 5(4 + 2\xi) + 3]}_{F(\xi)} d\xi$$

$$I = w_1 F(\xi_1) + w_2 F(\xi_2) = F\left(\frac{1}{\sqrt{3}}\right) + F\left(\frac{-1}{\sqrt{3}}\right)$$

$$I = (1)(50.64445) + (1)(110.68888) = 161.3333$$



# Numerical Integration: Gaussian Quadrature

## Two Dimensional Product Gauss Rules

Canonical form of integral:

$$\int_{-1}^1 \int_{-1}^1 F(\xi, \eta) d\xi d\eta = \int_{-1}^1 d\eta \int_{-1}^1 F(\xi, \eta) d\xi$$

Gauss integration rules with  $p_1$  points in the  $\xi$  direction and  $p_2$  points in the  $\eta$  direction:

$$\int_{-1}^1 \int_{-1}^1 F(\xi, \eta) d\xi d\eta = \int_{-1}^1 d\eta \int_{-1}^1 F(\xi, \eta) d\xi \approx \sum_{i=1}^{p_1} \sum_{j=1}^{p_2} w_i w_j F(\xi_i, \eta_j)$$

Usually  $p_1 = p_2 = p$

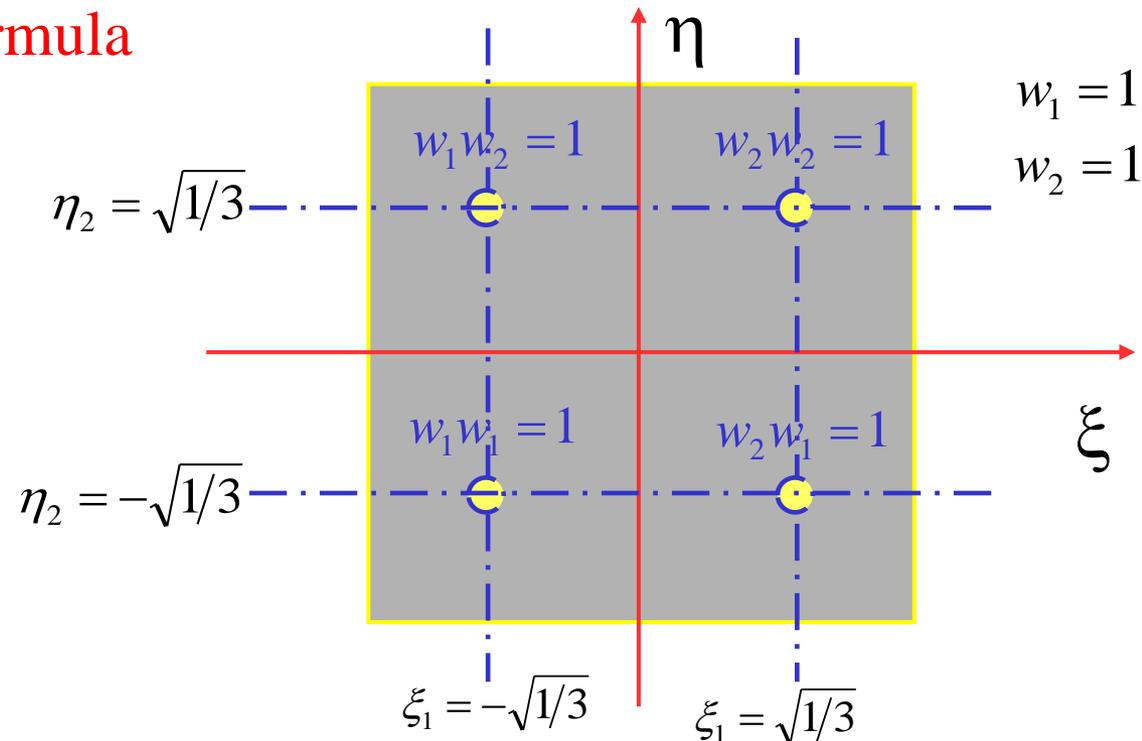
## 2-Dimensional Integration: Gaussian Quadrature

$$\int_{-1}^1 \int_{-1}^1 f(\xi, \eta) d\xi d\eta \cong \int_{-1}^1 \left[ \sum_{i=1}^n w_i f(\xi_i, \eta) \right] d\eta \approx \sum_{j=1}^n \sum_{i=1}^n w_j w_i f(\xi_i, \eta_j)$$

### 2-D Integration 2-point formula

$$\int_{-1}^1 \int_{-1}^1 f(\xi, \eta) d\xi d\eta \cong$$

$$\begin{aligned} & w_1 w_1 f(\xi_1, \eta_1) \\ & + w_2 w_1 f(\xi_2, \eta_1) \\ & + w_1 w_2 f(\xi_1, \eta_2) \\ & + w_2 w_2 f(\xi_2, \eta_2) \end{aligned}$$

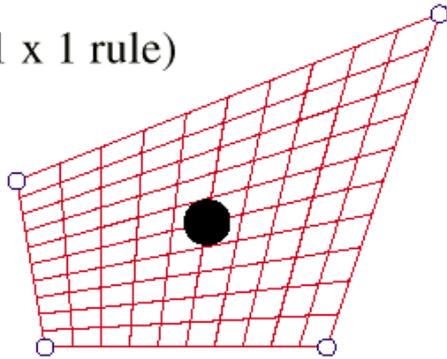




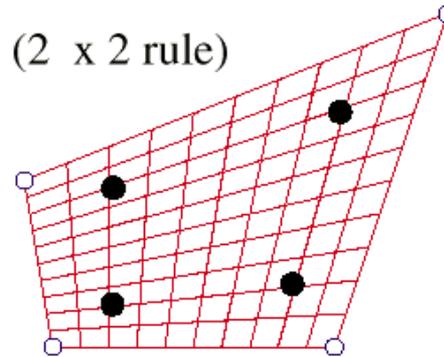
# Numerical Integration: Gaussian Quadrature

## Graphical Representation of the First Four 2D Product-Type Gauss Integration Rules

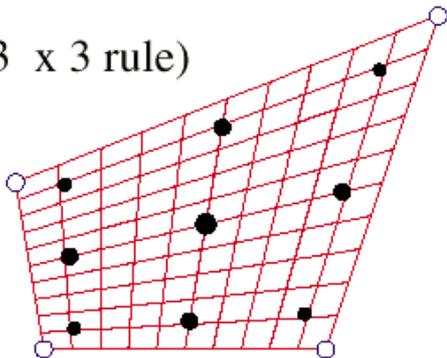
$p = 1$  (1 x 1 rule)



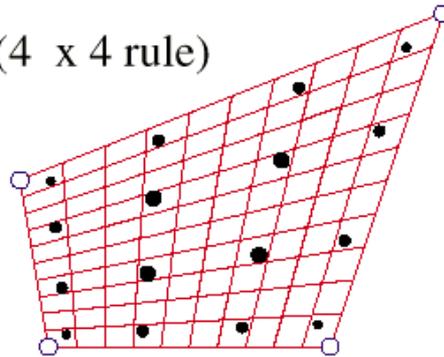
$p = 2$  (2 x 2 rule)



$p = 3$  (3 x 3 rule)



$p = 4$  (4 x 4 rule)



With Equal # of Points  $p$  in Each Direction

## Integration of Stiffness Matrix

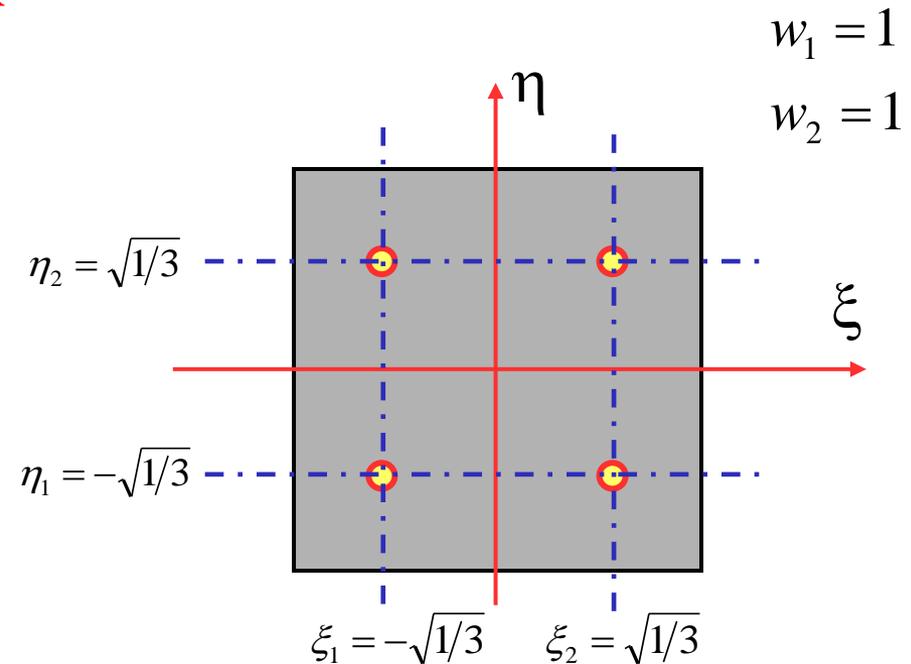
$$\mathbf{k} = t \int_A \mathbf{B}^T \mathbf{D} \mathbf{B} dA$$

$$= t \int_{-1}^1 \int_{-1}^1 \mathbf{B}^T \mathbf{D} \mathbf{B} \det J d\xi d\eta$$

$$k_{ij} = t \int_{-1}^1 \int_{-1}^1 g_{ij}(\xi, \eta) d\xi d\eta$$

$$= w_1 w_1 g_{ij}(\xi_1, \eta_1) + w_2 w_1 g_{ij}(\xi_2, \eta_1) + w_1 w_2 g_{ij}(\xi_1, \eta_2) + w_2 w_2 g_{ij}(\xi_2, \eta_2)$$

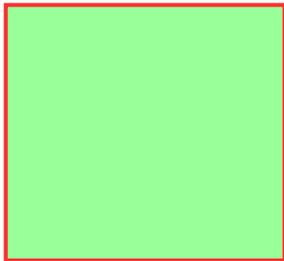
$$= g_{ij}(\xi_1, \eta_1) + g_{ij}(\xi_2, \eta_1) + g_{ij}(\xi_1, \eta_2) + g_{ij}(\xi_2, \eta_2)$$



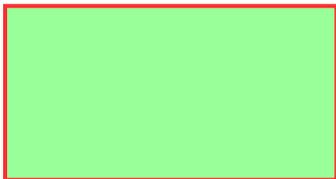


# Numerical Integration: Gaussian Quadrature

## Modeling Issues: Element Shape

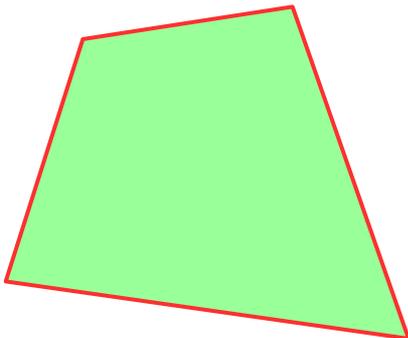


Square : Optimum Shape  
Not always possible to use



Rectangles:  
Rule of Thumb  
Ratio of sides  $< 2$

Larger ratios  
may be used  
with caution



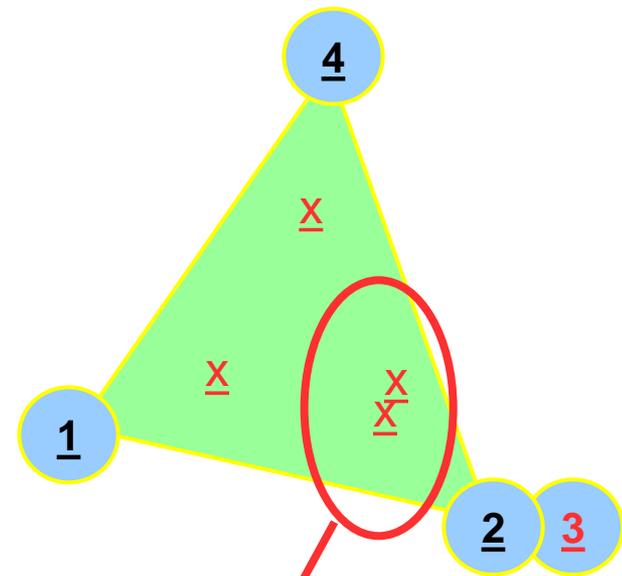
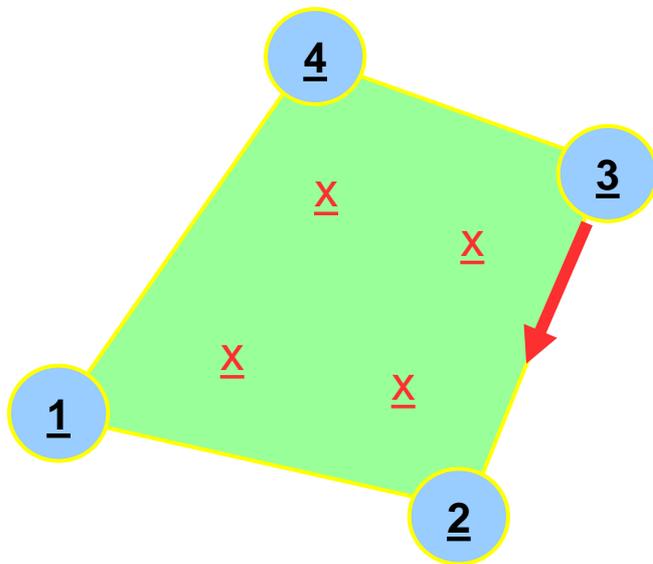
Angular Distortion  
Internal Angle  $< 180^\circ$



# Numerical Integration: Gaussian Quadrature

## Modeling Issues: Degenerate Quadrilaterals

### Coincident Corner Nodes

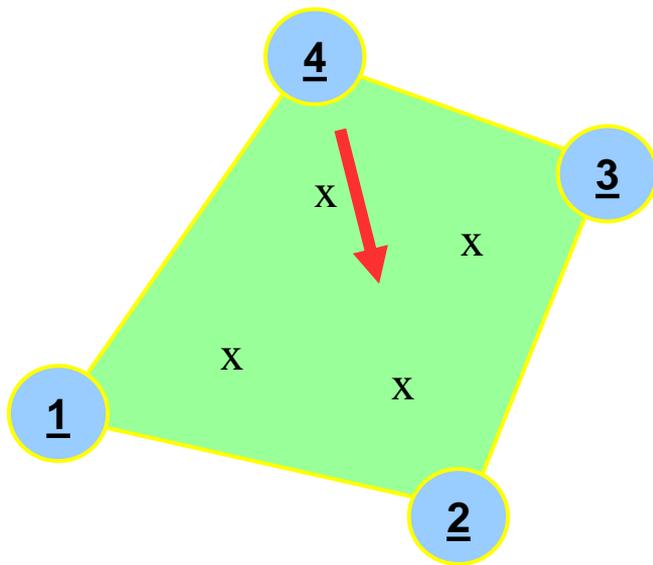


Integration Bias

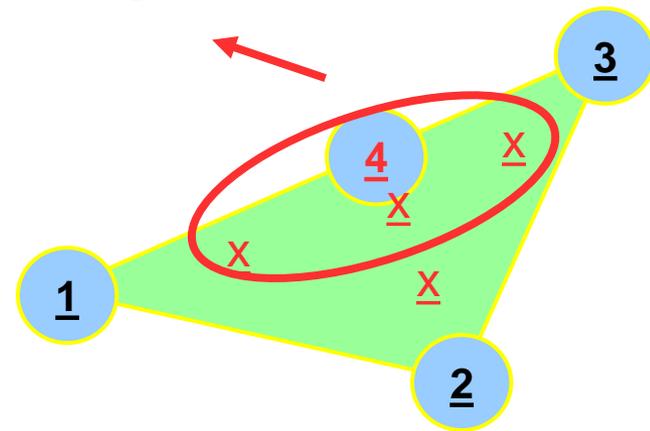
Less accurate

## Modeling Issues: Degenerate Quadrilaterals

Three nodes collinear



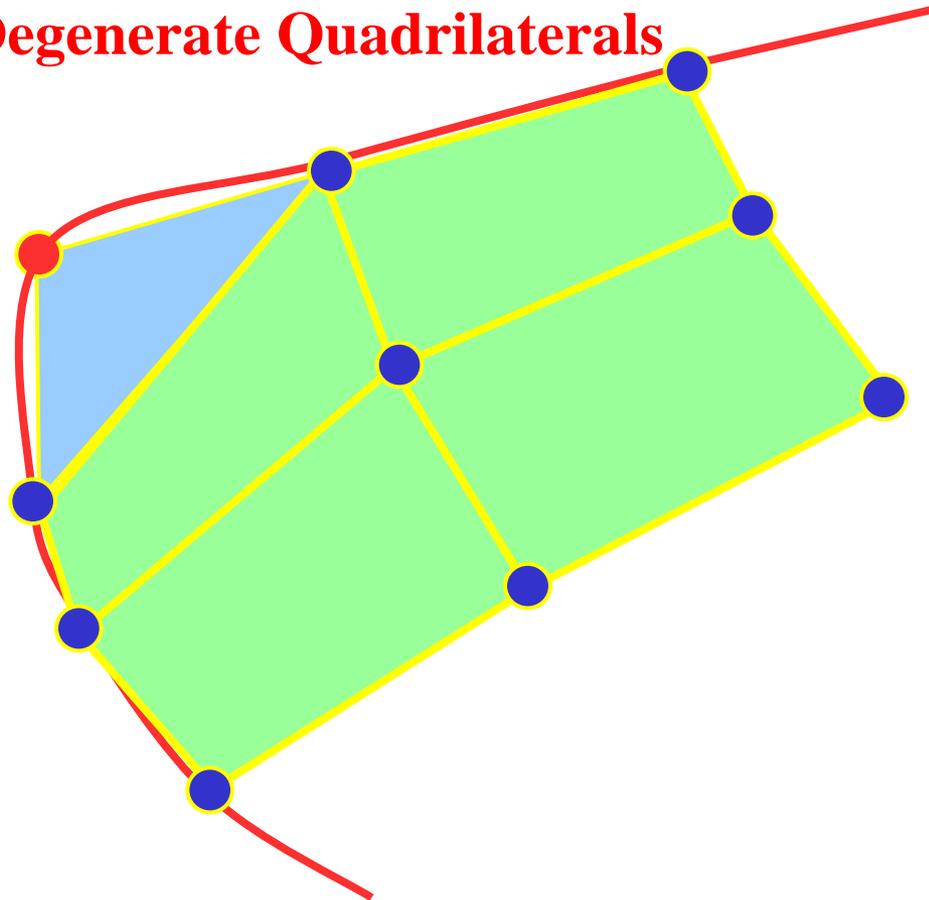
Integration Bias



Less accurate

## Modeling Issues: Degenerate Quadrilaterals

2 nodes



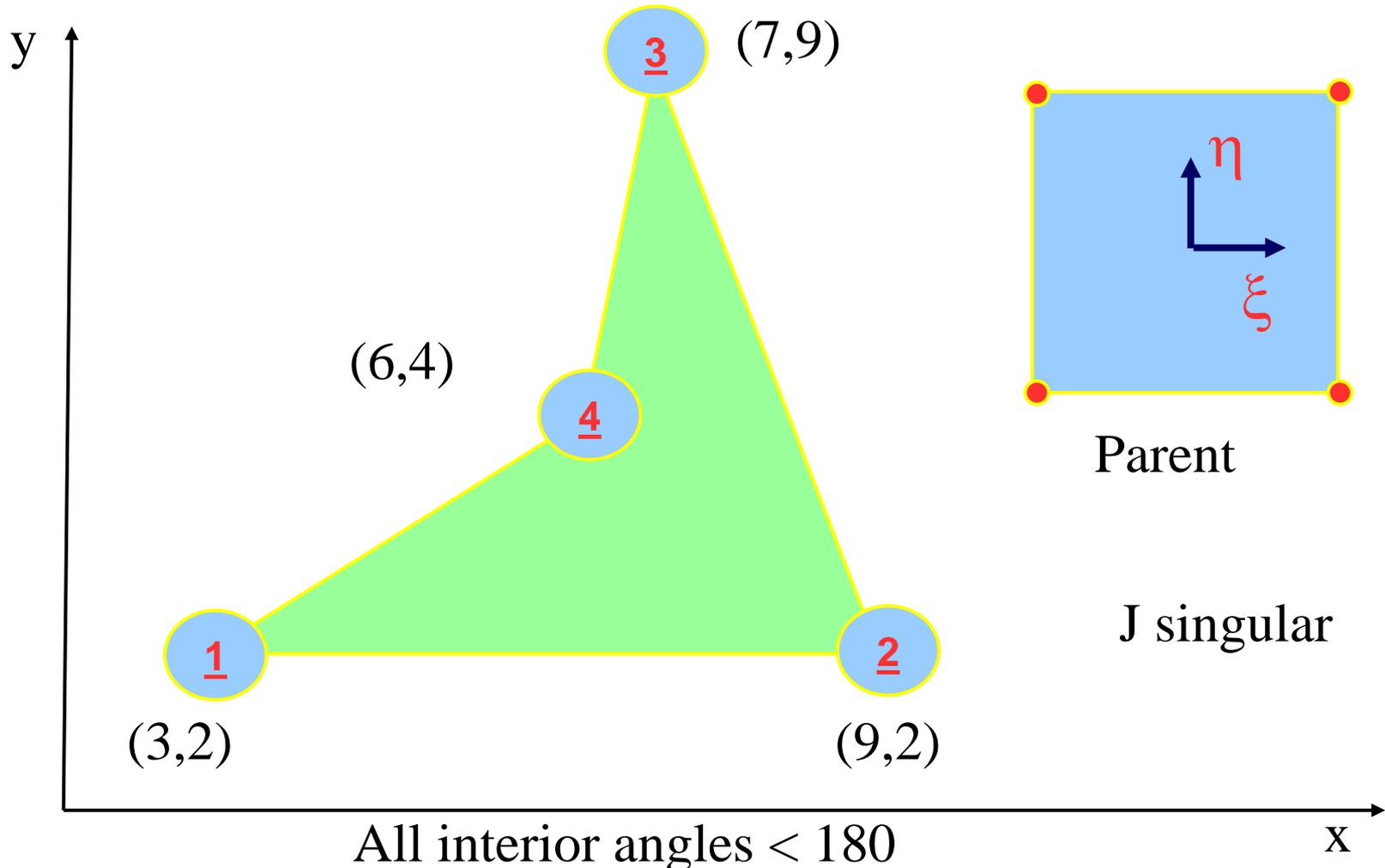
Use only as necessary to improve representation of geometry  
Do not use in place of triangular elements



# Numerical Integration: Gaussian Quadrature

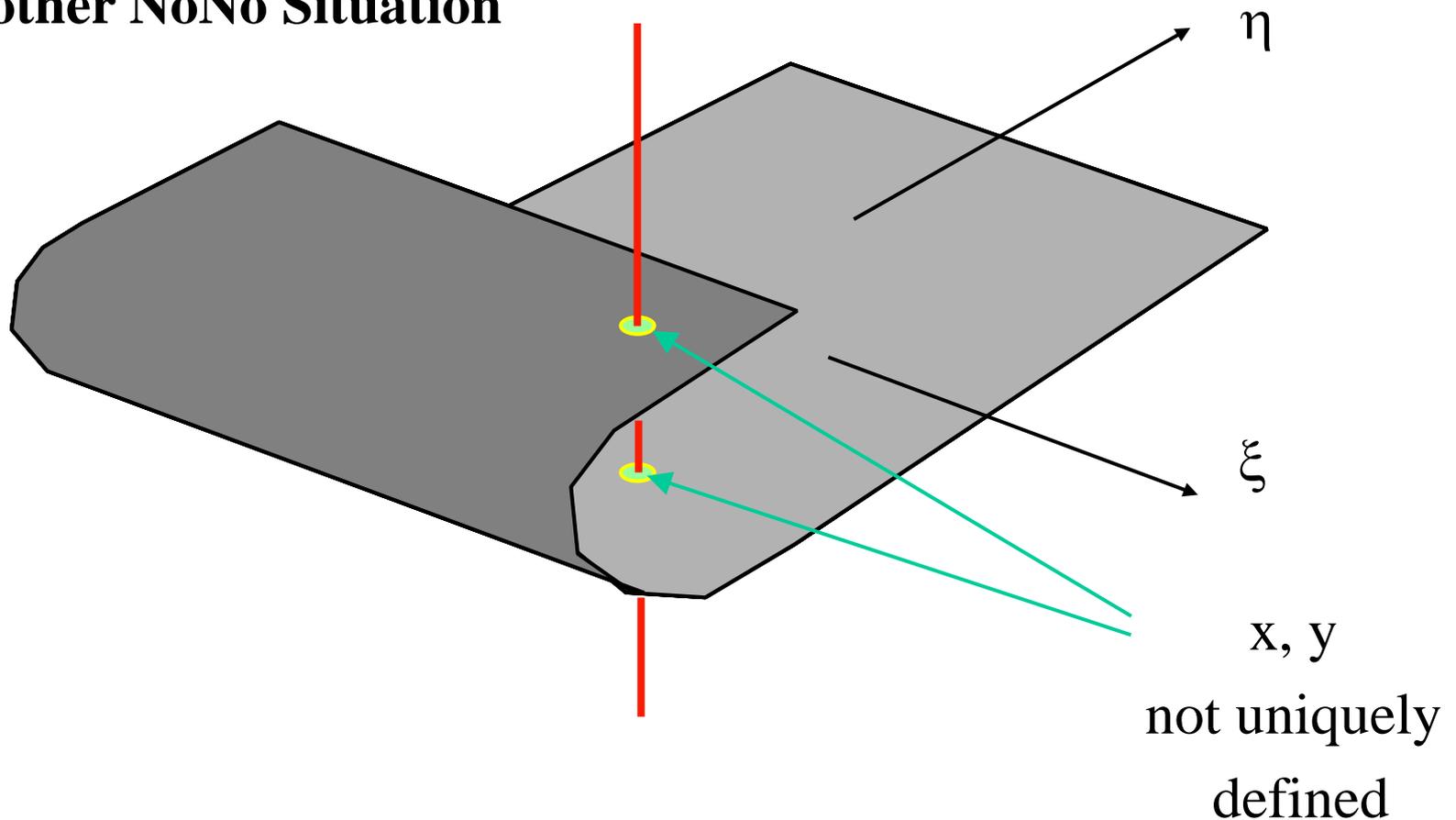
## Modeling Issues: Degenerate Quadrilaterals

## A NoNo Situation



## Modeling Issues: Degenerate Quadrilaterals

### Another NoNo Situation



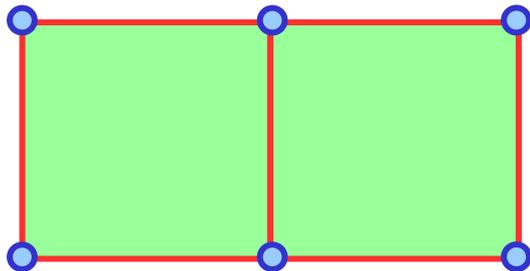
## Convergence Considerations

For monotonic convergence of solution; Requirements

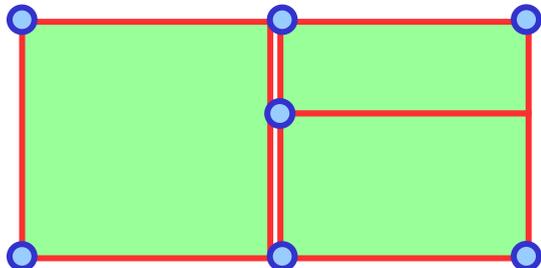
Elements (mesh) must be compatible

Elements must be complete

Mesh Compatibility

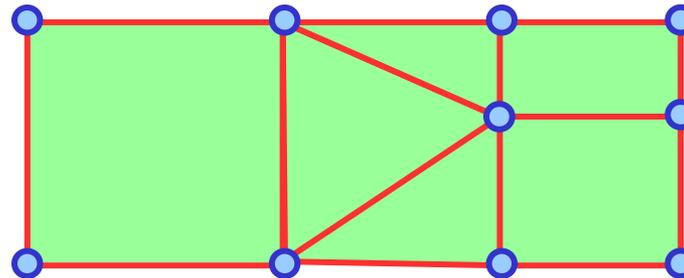


OK



NO!

Mesh compatibility - Refinement



Acceptable Transition

Compatibility of displacements OK

Stresses?



# Numerical Integration: Gaussian Quadrature

## Gauss integration

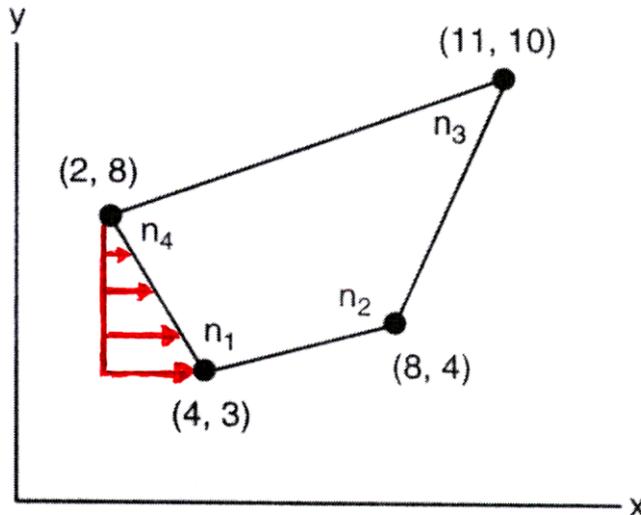
- For evaluation of integrals in  $\mathbf{k}$  (in practice)

In 1 direction: 
$$I = \int_{-1}^{+1} f(\xi) d\xi = \sum_{j=1}^m w_j f(\xi_j)$$

$m$  gauss points gives exact solution of polynomial integrand of  $n = 2m - 1$

In 2 directions: 
$$I = \int_{-1}^{+1} \int_{-1}^{+1} f(\xi, \eta) d\xi d\eta = \sum_{i=1}^{n_x} \sum_{j=1}^{n_y} w_i w_j f(\xi_i, \eta_j)$$

## Example:



$$\mathbf{t}(x, y) = \begin{pmatrix} 0.4 * (8 - y) \\ 0 \end{pmatrix} \text{ ksi}$$

- Given: 4-node plane stress element has  $E = 30,000$  ksi,  $\nu = 0.25$ ,  $h = 0.50$  in, no body force, and surface traction shown.
- Required: Find  $\mathbf{k}$  and  $\mathbf{f}$ . Use 2 x 2 Gauss quadrature for  $\mathbf{k}$ .



# Numerical Integration: Gaussian Quadrature

## Solution:

➤ Isoparametric mapping:

$$\begin{aligned}
 x &= \frac{1}{4}(1-\xi)(1-\eta)x_1 + \frac{1}{4}(1+\xi)(1-\eta)x_2 + \frac{1}{4}(1+\xi)(1+\eta)x_3 + \frac{1}{4}(1-\xi)(1+\eta)x_4 \\
 &= \frac{1}{4}(1-\xi)(1-\eta)*4 + \frac{1}{4}(1+\xi)(1-\eta)*8 + \frac{1}{4}(1+\xi)(1+\eta)*11 + \frac{1}{4}(1-\xi)(1+\eta)*2 \\
 &= \frac{25}{4} + \frac{13}{4}\xi + \frac{1}{4}\eta + \frac{5}{4}\xi\eta;
 \end{aligned}$$

$$\begin{aligned}
 y &= \frac{1}{4}(1-\xi)(1-\eta)*3 + \frac{1}{4}(1+\xi)(1-\eta)*4 + \frac{1}{4}(1+\xi)(1+\eta)*10 + \frac{1}{4}(1-\xi)(1+\eta)*8 \\
 &= \frac{25}{4} + \frac{3}{4}\xi + \frac{11}{4}\eta + \frac{1}{4}\xi\eta;
 \end{aligned}$$

➤ Jacobian matrix and Jacobian:

$$\mathbf{J} = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial y}{\partial \xi} \\ \frac{\partial x}{\partial \eta} & \frac{\partial y}{\partial \eta} \end{bmatrix} = \begin{bmatrix} \frac{13}{4} + \frac{5}{4}\eta & \frac{3}{4} + \frac{1}{4}\eta \\ \frac{1}{4} + \frac{5}{4}\xi & \frac{11}{4} + \frac{1}{4}\xi \end{bmatrix}; \quad J = \det \mathbf{J} = \frac{35}{4} - \frac{1}{8}\xi + \frac{27}{8}\eta.$$



# Numerical Integration: Gaussian Quadrature

➤ **B** matrix:

$$[B(\xi, \eta)] = \frac{1}{|\mathbf{J}|} [B_1 \quad B_2 \quad B_3 \quad B_4]$$

$$[B_i] = \begin{bmatrix} a(N_{i,\xi}) - b(N_{i,\eta}) & 0 \\ 0 & c(N_{i,\eta}) - d(N_{i,\xi}) \\ c(N_{i,\eta}) - d(N_{i,\xi}) & a(N_{i,\xi}) - b(N_{i,\eta}) \end{bmatrix}$$

➤ **B** matrix:

$$N_{1,\xi} = \frac{\partial N_1}{\partial \xi} = \frac{-1(1-\eta)}{4} = \frac{(\eta-1)}{4}$$

$$N_{1,\eta} = \frac{\partial N_1}{\partial \eta} = \frac{(1-\xi)(-1)}{4} = \frac{(\xi-1)}{4}$$

$$N_{2,\xi} = \frac{\partial N_2}{\partial \xi} = \frac{(1)(1-\eta)}{4} = \frac{(1-\eta)}{4}$$

$$N_{2,\eta} = \frac{\partial N_2}{\partial \eta} = \frac{(1+\xi)(-1)}{4} = \frac{-(\xi+1)}{4}$$

$$N_{3,\xi} = \frac{\partial N_3}{\partial \xi} = \frac{(1)(1+\eta)}{4} = \frac{(1+\eta)}{4}$$

$$N_{3,\eta} = \frac{\partial N_3}{\partial \eta} = \frac{(1+\xi)(1)}{4} = \frac{(\xi+1)}{4}$$

$$N_{4,\xi} = \frac{\partial N_4}{\partial \xi} = \frac{(-1)(1+\eta)}{4} = \frac{-(1+\eta)}{4}$$

$$N_{4,\eta} = \frac{\partial N_4}{\partial \eta} = \frac{(1-\xi)(1)}{4} = \frac{(1-\xi)}{4}$$

$$a = 1/4 \left[ y_1 (\xi - 1) + y_2 (-\xi - 1) + y_3 (\xi + 1) + y_4 (1 - \xi) \right]$$

$$b = 1/4 \left[ y_1 (\eta - 1) + y_2 (1 - \eta) + y_3 (\eta + 1) + y_4 (-1 - \eta) \right]$$

$$c = 1/4 \left[ x_1 (\eta - 1) + x_2 (1 - \eta) + x_3 (\eta + 1) + x_4 (-1 - \eta) \right]$$

$$d = 1/4 \left[ x_1 (\xi - 1) + x_2 (-\xi - 1) + x_3 (\xi + 1) + x_4 (1 - \xi) \right]$$



# Numerical Integration: Gaussian Quadrature

➤ **B** matrix:

$$\mathbf{B} = \frac{1}{70 - \xi + 27\eta} \times \begin{bmatrix} -4+6\eta-2\xi & 0 & 7-5\eta+2\xi & 0 & 4+5\eta-\xi & 0 & -7-6\eta+\xi & 0 \\ 0 & -6-3\eta+9\xi & 0 & -7-2\eta-9\xi & 0 & 6+2\eta+4\xi & 0 & 7+3\eta-4\xi \\ -6-3\eta+9\xi & -4+6\eta-2\xi & -7-2\eta-9\xi & 7-5\eta+2\xi & 6+2\eta+4\xi & 4+5\eta-\xi & 7+3\eta-4\xi & -7-6\eta+\xi \end{bmatrix}$$



# Numerical Integration: Gaussian Quadrature

➤ **k** matrix:

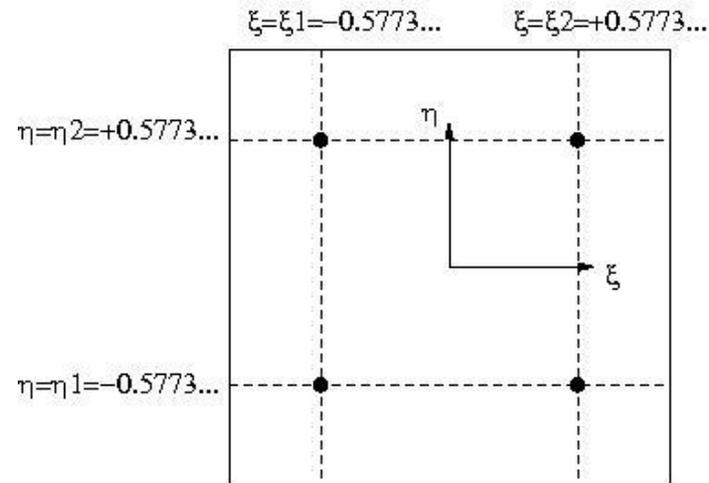
$$\mathbf{E} = \begin{bmatrix} 32000 & 8000 & 0 \\ 8000 & 32000 & 0 \\ 0 & 0 & 12000 \end{bmatrix} \text{ ksi};$$

$$\mathbf{k} = (0.5 \text{ in}) \int_{-1}^1 \int_{-1}^1 \mathbf{B}^T \mathbf{E} \mathbf{B} * J d\xi d\eta$$

$$= \int_{-1}^1 \int_{-1}^1 \frac{8}{70-\xi+27\eta} * \underbrace{\begin{bmatrix} 31.25*(236-276\eta-196\xi+315\eta^2-354\eta\xi+275\xi^2) & \dots & 31.25*(70+231\eta-203\xi+90\eta^2-231\eta\xi+43\xi^2) \\ \vdots & \ddots & \vdots \\ \text{sym} & \dots & 31.25*(539+588\eta-490\xi+180\eta^2-228\eta\xi+131\xi^2) \end{bmatrix}}_{[\mathbf{k}'(\xi,\eta)]} d\xi d\eta$$

➤ 2 x 2 Gauss quadrature:

$$W_i = W_j = 1; \quad i, j = 1, 2.$$



$$\mathbf{k} \approx \sum_{i=1}^2 \sum_{j=1}^2 W_i W_j * [\mathbf{k}'(\xi = \xi_i, \eta = \eta_j)] = [\mathbf{k}'(-\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}})] + [\mathbf{k}'(-\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})] + [\mathbf{k}'(\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}})] + [\mathbf{k}'(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}})]$$

$$\therefore \mathbf{k} \approx \begin{bmatrix} 7028.9 & \dots & 1260.6 \\ \vdots & \ddots & \vdots \\ 1260.6 & \dots & 8489.9 \end{bmatrix} \text{ kips/in.}$$

$$\text{Note: } \mathbf{k}_{exact} = \begin{bmatrix} 7136.6 & \dots & 1263.9 \\ \vdots & \ddots & \vdots \\ 1263.9 & \dots & 8499.0 \end{bmatrix} \text{ kips/in.}$$

➤ Element nodal forces: . . . .

## Problem 1

Figure (1) shows a four-node quadrilateral. The  $(x,y)$  coordinates of each node are given in the figure. The element displacement vector  $u$  is given as:  $U=[0,0,0.20,0,0.15,0.10,0,0.05]$

Find:

A- The  $x$ - $y$  coordinates of a point  $P$  whose location in the master element is given by

$$\xi = 0.5, \eta = 0.5$$

B- The  $u$  and  $v$  displacement of the point  $P$

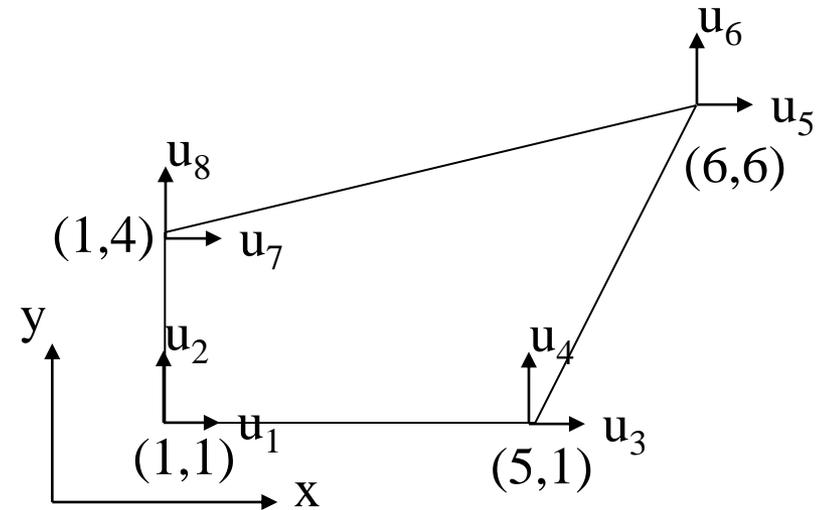


Figure (1)

## Problem 2

Using a 2 by 2 rule evaluate the following integral by Gaussian quadrature, where  $A$  denotes the region shown in Figure (1).

$$\iint_A (x^2 + xy^2) dx dy$$



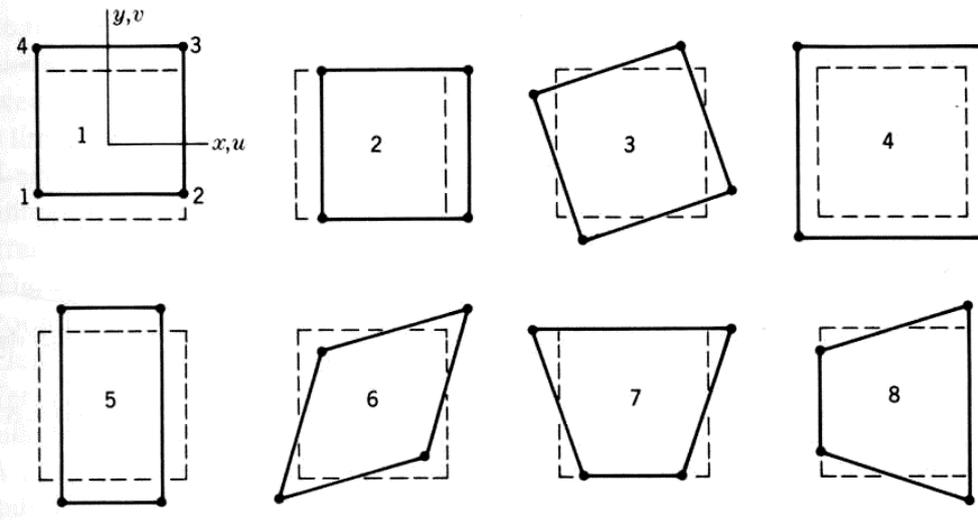
# Numerical Integration: Gaussian Quadrature

## Zero-Energy Modes (Mechanisms; Kinematic Modes) –

- ❖ Instabilities for an element (or group of elements) that produce deformation without any strain energy.
- ❖ Typically caused by using an inappropriately low order of Gauss quadrature.
- ❖ If present, will dominate the deformation pattern.
- ❖ Can occur for all 2D elements except the CST.

## Zero-Energy Modes –

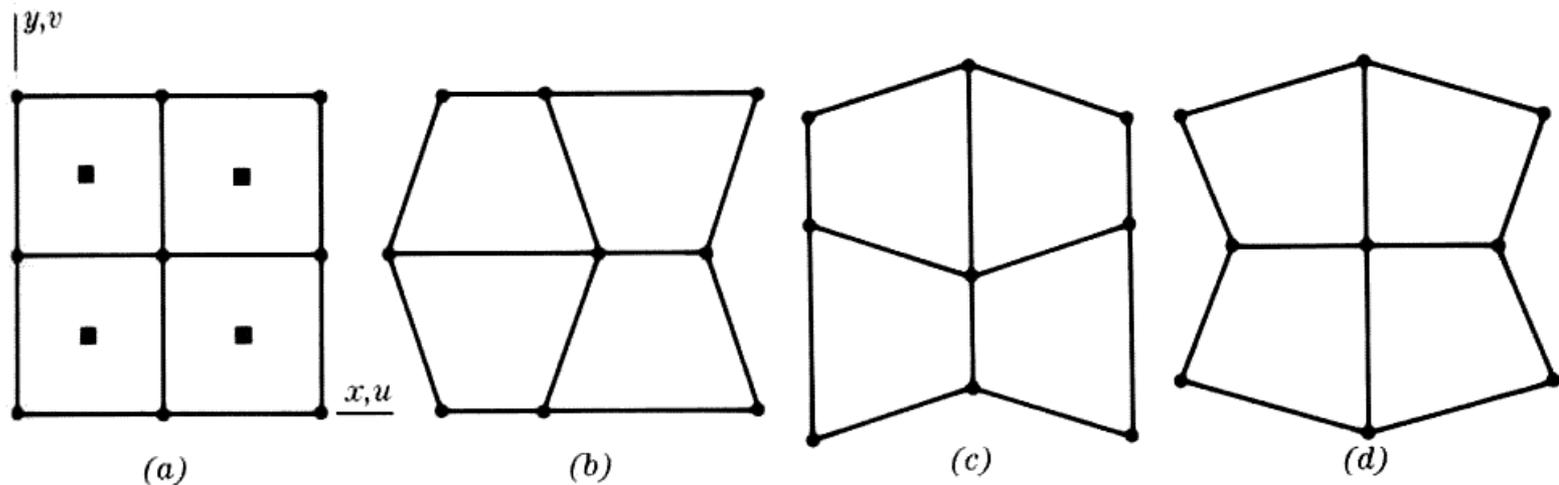
❖ Deformation modes for a bilinear quad:



- ❖ #1, #2, #3 = *rigid body modes*; can be eliminated by proper constraints.
- ❖ #4, #5, #6 = *constant strain modes*; always have nonzero strain energy.
- ❖ #7, #8 = *bending modes*; produce zero strain at origin.

## Zero-Energy Modes –

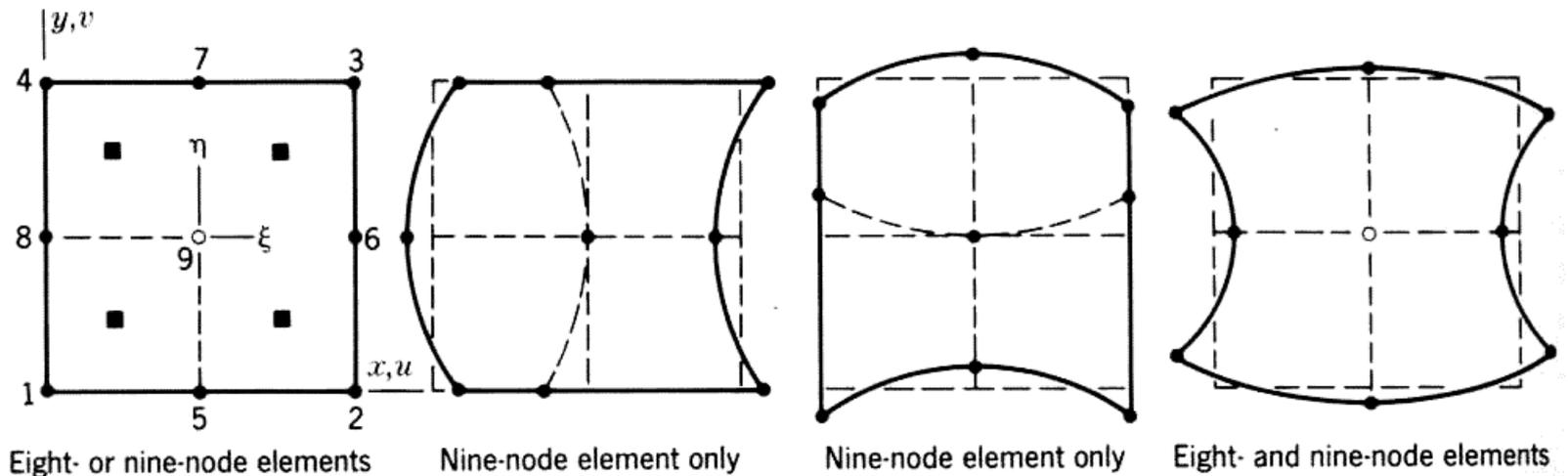
- ❖ Mesh instability for bilinear quads using order 1 quadrature:



“Hourglass modes”

## Zero-Energy Modes –

- ❖ Element instability for quadratic quadrilaterals using 2x2 Gauss quadrature:



“Hourglass modes”



## Zero-Energy Modes –

- ❖ How can you prevent this?
  - ❖ Use higher order Gauss quadrature in formulation.
  - ❖ Can artificially “stiffen” zero-energy modes via penalty functions.
  - ❖ Avoid elements with known instabilities!



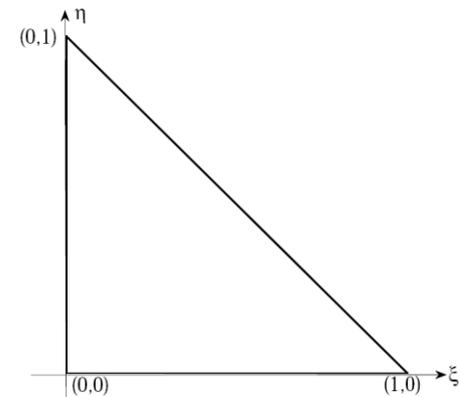
# Gauss Integration for Triangular Region

The gauss points for a triangular region differ from the square region considered earlier. The simplest one is the one-point rule at the centroid with weight  $w_1=1/2$  and  $\xi_1 = \eta_1 = \zeta_1 = 1/3$

$$K^{(e)} = t \int_{\Omega^e} B^T E B \det J d\xi d\eta = \frac{1}{2} \underbrace{t \bar{B}^T \bar{E} \bar{B} \det \bar{J}}_{\text{Evaluated at Gauss point}}$$

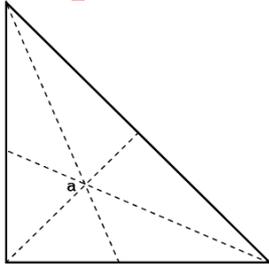
Evaluated at Gauss point

$$I = \int_0^1 \int_0^{1-\xi} f(\xi, \eta) d\eta d\xi \approx \sum_{i=1}^n w_i f(\xi_i, \eta_i)$$

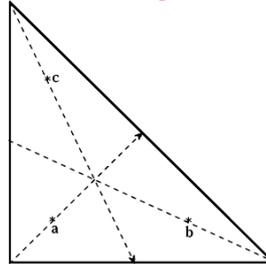


# Gauss Integration for Triangular Region

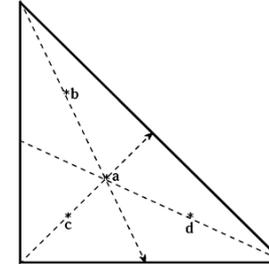
## First set of quadrature rules for triangular elements



(a) Linear  
 $a = \left(\frac{1}{3}, \frac{1}{3}\right), w = 1$

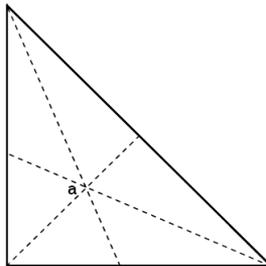


(b) Quadratic  
 $a = \left(\frac{1}{6}, \frac{1}{6}\right), w = \frac{1}{3}$   
 $b = \left(\frac{2}{3}, \frac{1}{6}\right), w = \frac{1}{3}$   
 $c = \left(\frac{1}{6}, \frac{2}{3}\right), w = \frac{1}{3}$

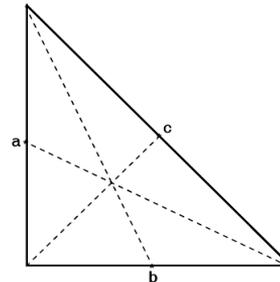


(c) Cubic  
 $a = \left(\frac{1}{3}, \frac{1}{3}\right), w = -\frac{27}{48}$   
 $b = \left(\frac{1}{5}, \frac{3}{5}\right), w = \frac{25}{48}$   
 $c = \left(\frac{1}{5}, \frac{1}{5}\right), w = \frac{25}{48}$   
 $d = \left(\frac{3}{5}, \frac{1}{5}\right), w = \frac{25}{48}$

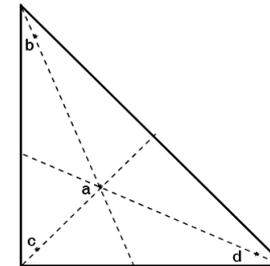
## Second set of quadrature rules for triangular elements



(a) Linear  
 $a = \left(\frac{1}{3}, \frac{1}{3}\right), w = 1$



(b) Quadratic  
 $a = \left(0, \frac{1}{2}\right), w = \frac{1}{3}$   
 $b = \left(\frac{1}{2}, 0\right), w = \frac{1}{3}$   
 $c = \left(\frac{1}{2}, \frac{1}{2}\right), w = \frac{1}{3}$



(c) Cubic  
 $a = \left(\frac{1}{3}, \frac{1}{3}\right), w = -\frac{27}{48}$   
 $b = \left(\frac{2}{15}, \frac{11}{15}\right), w = \frac{25}{48}$   
 $c = \left(\frac{2}{15}, \frac{2}{15}\right), w = \frac{25}{48}$   
 $d = \left(\frac{11}{15}, \frac{2}{15}\right), w = \frac{25}{48}$



# Gauss Integration for Triangular Region

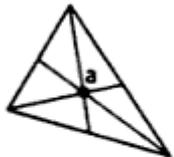
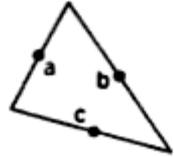
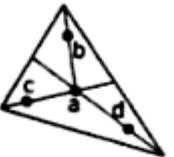
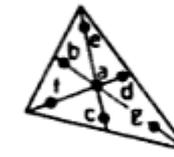
$$\int_0^1 \int_0^{1-\xi} f(\xi, \eta) d\eta d\xi \approx \sum_{i=1}^n w_i f(\xi_i, \eta_i)$$

No. of Points (n)	Weight $w_i$	Multiplicity	$\xi_i$	$\eta_i$	$\zeta_i$
One	1/2	1	1/3	1/3	1/3
Three	1/6	3	2/3	1/6	1/6
Three	1/6	3	1/2	1/2	0
Four	-9/32 25/96	1 3	1/3 3/5	1/3 1/5	1/3 1/5
Six	1/12	6	0.6590276223	0.231933685	0.109039009

Because of triangular symmetry, the Gauss point are occurred in group or *multiplicity* of one, three or six. For multiplicity of three if one Gauss point is at (2/3,1/6,1/6) then the other two Gauss points are located at (1/6,2/3,1/6) and (1/6,1/6,2/3). For multiplicity of six all six possible permutation of three coordinate are used.

TABLE 5.3. Numerical Integration Formulas for Triangles

Appendix

No.	Order	Figure	Rem.	Points	Triangular Coordinates	Weights $W_k$
1	Linear		$R = 0(h^2)$	$a$	$\frac{1}{3}, \frac{1}{3}, \frac{1}{3}$	1
2	Quadratic		$R = 0(h^3)$	$a$ $b$ $c$	$\frac{1}{2}, \frac{1}{2}, 0$ $0, \frac{1}{2}, \frac{1}{2}$ $\frac{1}{2}, 0, \frac{1}{2}$	$\frac{1}{3}$ $\frac{1}{3}$ $\frac{1}{3}$
3	Cubic		$R = 0(h^4)$	$a$ $b$ $c$ $d$	$\frac{1}{3}, \frac{1}{3}, \frac{1}{3}$ $0.6, 0.2, 0.2$ $0.2, 0.6, 0.2$ $0.2, 0.2, 0.6$	$-27/48$ $25/48$ $25/48$ $25/48$
5	Quintic		$R = 0(h^6)$	$a$ $b$ $c$ $d$ $e$ $f$ $g$	$\frac{1}{3}, \frac{1}{3}, \frac{1}{3}$ $\alpha_1, \beta_1, \beta_1$ $\beta_1, \alpha_1, \beta_1$ $\beta_1, \beta_2, \beta_2$ $\alpha_2, \beta_2, \beta_2$ $\beta_2, \alpha_2, \beta_2$ $\beta_2, \beta_2, \alpha_2$	0.225 0.13239415 0.12593918

With:

$\alpha_1 = 0.05961587$   
 $\beta_1 = 0.47014206$   
 $\alpha_2 = 0.79742699$   
 $\beta_2 = 0.10128651$