Problem 1

Consider an infinitely long column of liquid of density ρ , radius a, and interfacial surface tension γ rotating at uniform angular velocity Ω . The inviscid incompressible ($\rho = const.$) motion of the Euler equations in a system rotating at angular velocity Ω in dimensional (asterisk) coordinates are given by

$$\frac{D\mathbf{u}^*}{Dt} + 2\Omega \times \mathbf{u}^* = -\frac{1}{\rho} \nabla^* p^* + \nabla^* \left(\frac{|\Omega \times \mathbf{r}^*|^2}{2} \right)$$
$$\nabla^* \cdot \mathbf{u}^* = 0$$

where we take $\Omega = \Omega \mathbf{k}$ for rotation about the z^* axis and \mathbf{r}^* is the position vector. Show for cylindrical coordinates (r^*, θ, z^*) with associated velocities (u^*, v^*, w^*) that the base flow is

where p_0^* is the pressure at $r^* = 0$. Assuming $p^* = p_{\infty}^*$ in the gas surrounding the liquid column $(r^* \ge a)$, show that the kinematic and dynamic free surface boundary conditions are

where η^* is the disturbed position of the free surface about $r^* = a$ and **n** is the outward normal to the interface. Normalizing disturbances by a, time by Ω^{-1} , velocities by Ωa , and pressure by $\rho\Omega^2 a^2$, show that the dimensionless equations are

$$\frac{Du}{Dt} - \frac{v^2}{r} - 2v = -\frac{\partial}{\partial r} \left(p - \frac{r^2}{2} \right)$$

$$\frac{Dv}{Dt} + \frac{uv}{r} + 2u = -\frac{1}{r} \frac{\partial p}{\partial \theta}$$

$$\frac{Dw}{Dt} = -\frac{\partial p}{\partial z}$$

$$\frac{1}{r} \frac{\partial (ru)}{\partial r} + \frac{1}{r} \frac{\partial v}{\partial \theta} + \frac{\partial w}{\partial z} = 0$$

Part A

Now investigate the temporal stability of the flow by positing disturbances of the form

$$\begin{pmatrix} u \\ v \\ w \\ p \\ \eta \end{pmatrix} = \begin{pmatrix} U \\ V \\ W \\ P \\ \eta_0 \end{pmatrix} e^{i(kz+n\theta)+st}$$

wherein $s = \sigma + i\omega$ and U(r), V(r), W(r) and P(r) are radial eigenfunctions. Note that n = 0 for $k \neq 0$ describes axisymmetric disturbances; k = 0 for $n \neq 0$ describes planar disturbances; and $n \neq 0$ with $k \neq 0$ describes nonaxisymmetric (spiral) disturbances ask sketched in Figure 1. Show that

$$U = -\frac{1}{s^2 + 4} \left[sP_r + \frac{2in}{r} P \right]$$

$$V = \frac{1}{s^2 + 4} \left[2P_r - \frac{ins}{r} P \right]$$

$$W = -\frac{ik}{s} P$$

and

$$P_{rr} + \frac{1}{r}P_r - \left[\frac{n^2}{r^2} + \beta^2\right]P = 0$$
 where $\beta^2 = \frac{k^2(s^2 + 4)}{s^2}$

with solution finite at r = 0 given by

$$P(r) = AI_n(\beta r).$$

Finally, use the kinematic and dynamic boundary conditions to obtain the eigenvalue equation

$$\beta \frac{I_n'(\beta)}{I_n(\beta)} = \frac{s^2 + 4}{1 + (1 - k^2 - n^2)L} - \frac{2in}{s} \tag{1}$$

where primes denote differentiation with respect to r. Hence show that for axisymmetric disturbances one finds

$$\beta \frac{I_n'(\beta)}{I_n(\beta)} = -\frac{s^2 + 4}{\psi_1} \quad \text{where} \quad \psi_1 = -1 + L(k^2 - 1)$$
 (2)

Verify that in the limit $\Omega \to 0$ one recovers the eigenvalue equation found by Rayleigh (1879) for axisymmetric disturbances of a nonrotating fluid column. (note that in the nondimensionalization s^* is normalized by Ω .

with boundary conditions

$$u = \eta_t + \frac{v}{r} \eta_\theta + w \eta_z$$

$$p - p_\infty = L \left[\frac{1}{r} \frac{\partial}{\partial r} \left(\frac{r}{D} \right) - \frac{1}{r^2} \frac{\partial}{\partial \theta} \left(\frac{\eta_\theta}{D} \right) - \frac{\partial}{\partial z} \left(\frac{\eta_z}{D} \right) \right]$$

$$(r = 1 + \eta)$$

where

$$D=\sqrt{1+\frac{1}{r^2}\eta_\theta^2+\eta_z^2}$$

and the base flow is $\mathbf{u} = 0$, $p = p_0 + r^2/2$ for $0 \le r \le 1$.

Investigate stability to small disturbances

$$u = \epsilon u'$$
 $\eta = \epsilon \eta'$ $v = \epsilon v'$ $v = \epsilon w'$ $p = p_0 + \frac{r^2}{2} + \epsilon p'$

to obtain the linearized system (dropping primes)

$$\begin{split} \frac{\partial u}{\partial t} - 2v &= -\frac{\partial p}{\partial r} \\ \frac{\partial v}{\partial t} + 2u &= -\frac{1}{r} \frac{\partial p}{\partial \theta} \\ \frac{\partial w}{\partial t} &= -\frac{\partial p}{\partial z} \\ \frac{1}{r} \frac{\partial (ru)}{\partial r} + \frac{1}{r} \frac{\partial v}{\partial \theta} + \frac{\partial w}{\partial z} &= 0 \end{split}$$

with boundary conditions

$$p$$
 finite $@ r = 0$
 $u = \eta_t$ $@ r = 1$
 $p = -[\eta + L(\eta + \eta_{\theta\theta} + \eta_{zz})]$ $@ r = 1$

where $L = \gamma/\rho\Omega^2 a^3$ is the parameter introduced by Hocking (Mathematica, 7, 1-9, 1960). Actually L is a rotating Weber number.

Part B

Show, without explicitly solving (2) for axisymmetric disturbances, that information about stability may be obtained by writing the n = 0 problem in the form

$$\frac{d}{dr}\left(\frac{1}{r}\frac{dG}{dr}\right) - \frac{\beta^2}{r}G = 0\tag{3a}$$

where G(r) = rU(r) and the associated boundary conditions are

$$G(0) = 0 (3b)$$

$$G_{\mathbf{r}}(1) + \frac{k^2}{s^2} \psi_1 G(1) = 0.$$
 (3c)

Derive the functional for s^2 by first multiplying (3a) by G, integrating over the domain [0, 1] using integration by parts, and applying bounary conditions (3b,c). Hence show that

$$-\frac{s^2}{k^2} = \frac{4\int_0^1 \frac{G^2}{r} dr + \psi_1 G^2(1)}{\int_0^1 \left\{\frac{1}{r} [G_r^2 + k^2 G^2]\right\} dr}$$

and show that this infers that axisymmetrically disturbed flow is stable only if $\psi_1 > 0$. Show also that instability is possible only for wavenumbers below a cutoff wavenumber k_0 given by

$$k_0 = \sqrt{1 + \frac{1}{L}}.$$

Growth rate curves for n=0 computed (2) for $s=\sigma$ plotted in Figure 2 exhibit a common intersection at k=1. Show using (2) that the crossover occurs at $\sigma=0.43323$ and verify, using the numerical values in Figure 2 for at least one curve, that all unstable growth rates lie in the region $0 < k < k_0$.

A cross plot of the maximum growth rate σ_m and the associated critical wavenumbers k_c obtained from many numerical calculations at different values of L is given in Figure 3. Note that all k_c satisfy $k_c < k_0$ as must be the case. Comparison with the asymptotic results of Rayleigh (1879) for $L \to \infty$ and Pedley (1967) for $L \to 0$ are also shown in the figure.

Part C

Spiral and planar disturbances can compete for instability if their maximum growth rates exceed (for any ω) the values σ_m obtained in Figure 3. Numerical calculations show that $n \geq 1$ spiral disturbances have values of σ_m less than those for axisymmetric disturbances at each L. Planar disturbances, however, do compete for instability at sufficiently low L.

Demonstrate this result by showing first that planar disturbances $(k = \beta = 0)$ are governed by the boundary value problem

$$r^{2}P_{rr} + rP_{r} - n^{2}P = 0$$
 $P = \frac{1 + L(1 - n^{2})}{s^{2} + 4} \left(P_{r} + \frac{2in}{s}P\right) \quad @ \quad r = 1$
 $P \quad \text{finite} \quad @ \quad r = 0$

and show that the solution finite at r = 0 is

$$P(r) = Cr^n \qquad (n \ge 1).$$

Also show that solution of the eigenvalue relation gives

$$s = i \pm \sqrt{n\psi_2 - 1}$$

where now $\psi_2 = 1 + L(1 - n^2)$. Thus show that the flow is neutrally stable for n = 1 and unstable for

$$L<\frac{1}{n(n+1)} \qquad (n\geq 2).$$

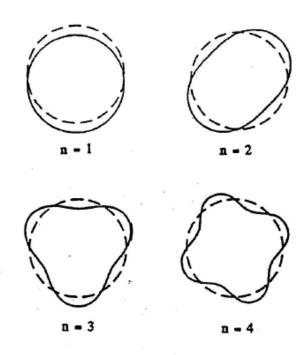
Hence fluid disturbances rotating at $\omega^* = \Omega$ with respect to the rotating frame have growth rates $\sigma = \pm \sqrt{n\psi_2 - 1}$. Also show that n = 2 instability gives way to higher planar modes (n = 3, 4, 5 etc.) as $L \to 0$. Show that these transition points L_t between the unstable planar modes are given by

$$L_t = \frac{1}{3n(n+1)}.$$

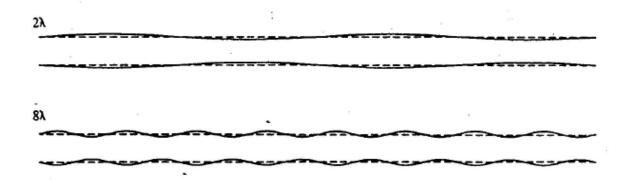
Finally, use the preceding results to show that the planar mode growth rates first exceed the maximum axisymmetric growth rates at n=2. This is most easily done by calculating the crossover point between mode 2 grow rates with the $(L \to 0)$ asymptotic results plotted in Figure 3; the equations describing the asymptotic curves σ_m and k_c are given by (Pedley, 1967), viz.

$$\sigma_m^2 = \frac{2(1+L)}{27L + [(1+30L+3L^2+L^3)]^{1/2}}$$
$$k_c^2 = \frac{1+L}{3L}.$$

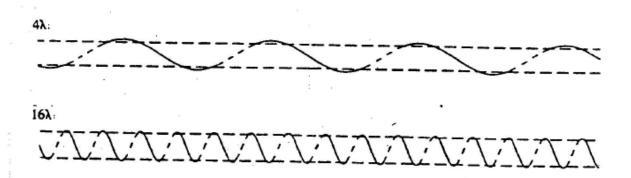
Find the approximate crossover value L_c and compare it with the numerically computed crossover value $L_c = 0.1053$ and hence show that the stability diagram at low values of L looks as shown in Figure 4.



(a) Planar modes: k = 0



(b) Axisymmetric modes: n = 0



(c) Spiral modes

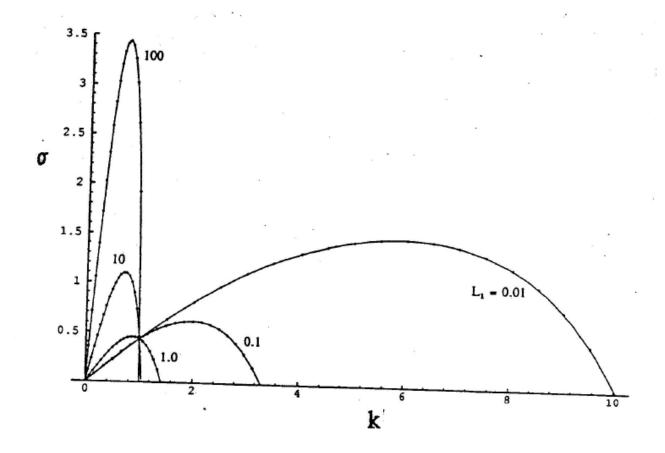
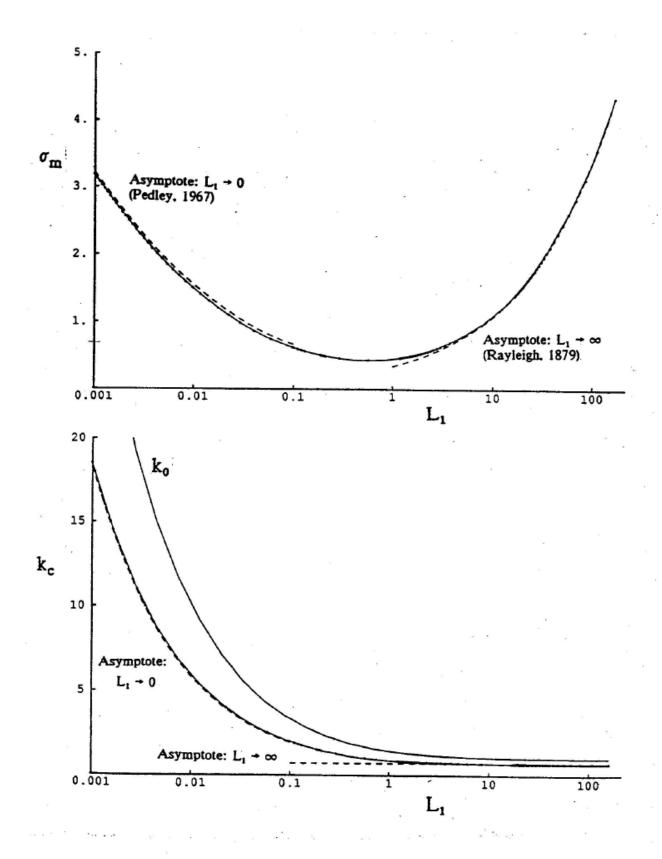


FIG. 2



F1G. 3

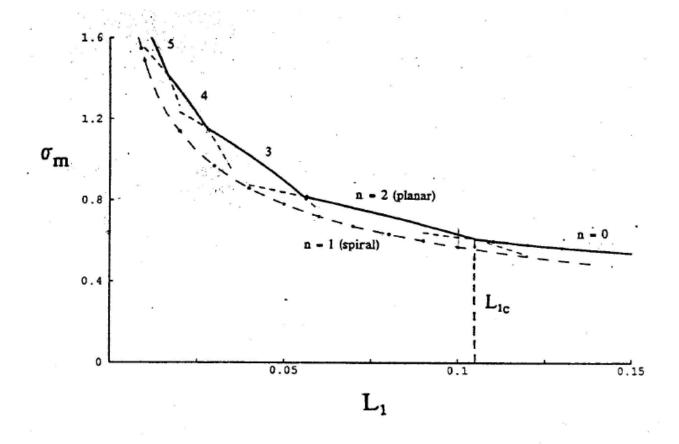


FIG. 4