Autumn
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Horaco

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Data analysis Steps that can be distinguished when analyzing data: a) Exploratory analyses 1) Initial examination of the data. 2) Relations explanatory variables and the response variable. 3) Relations among explanatory variables. 4) Conclusions based on the exploratory analysis. b) Building the model c) Model criticism d) Analysis using the final model.

a.1) Initial examination of the data - Why?? 1. Asses the structure of the data What is the sample size? How many variables are there? What type of variables (continuous, categorical) are there? 2. Data quality Are there missing observations? How were missing values treated? Are there any outliers?

Response variable (Y)
Continuous, binomial, count data...
Is a general linear model appropriate?
Explanatory variables (X)

• all quantitative - linear regression models
• all qualitative - analysis of variance models
• quantitative and qualitative - analysis of covariance fixed effects
co-variables

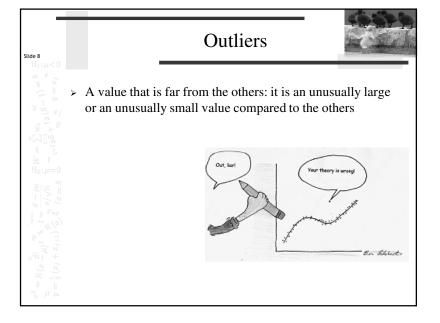
Missing data - check if there is a pattern.

- If the missingness is completely unrelated to the response or the predictor variables, there is no problem.
- If there is a pattern in the missing data, however, things become complicated.

Missing data - how are they coded? e.g. a missing value code of 0 or -99 for body weight of a cow will not be noticed by the software package but might have a big impact on the results.

Exploratory analysis

> Exploratory data analysis can be used to identify errors. Simple plots such as histograms or scatter plots of all variables (not only the response variable!!) can be used to look for weird data points – use common sense, e.g. negative body weights or animals died before they were born.



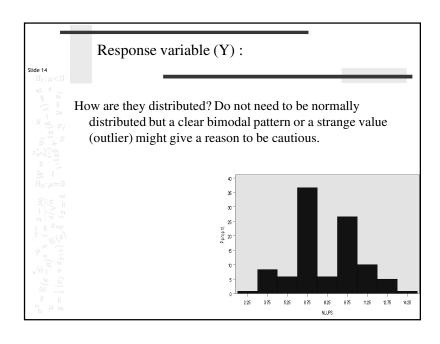
What to do – delete or keep in the analysis? 1. Was the value entered into the computer correctly? If there was an error in data entry, fix it. 2. Is there a justification to exclude the value resulting from that analysis? 3. Is the outlier caused by "normal" variation? The observation/individual may be different from the others. This may be the most exciting finding in your data!

> One way to identify univariate outliers is to convert all of the scores for a variable to standard scores. > If the sample size is small (80 or fewer cases), a case is an outlier if its standard score is ±2.5 or beyond. > If the sample size is larger than 80 cases, a case is an outlier if its standard score is ±3.0 or beyond

Example: Grazing behavior of sheep The researcher in this project is convinced that male sheep loop up more frequently while eating than female sheep (and also has a theory on why this should be the case). An undergraduate student spends many uncomfortable weeks in a hide near a field (so as not to disturb the sheep) and records the data for each observation on each of 3 male and 3 female sheep.

Research question: Do male sheep look up more frequently while eating than female sheep? Variables: DURAT: duration of feeding time in minutes NLUPS: the number of lookups SEX: coded as 1 for female and 2 for male SHEEP: coded as 1 to 6 OBSP: the number of the observation period from 1 to 20.

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$H_1: \mu < 0$,	Variabl	Le: NLUPS					
& S B			Моп	ients					
1-9 in [1]	N Mean Std Deviation Skewness Uncorrected S Coeff Variati	-0.03		Sum Weights Sum Observations Variance Kurtosis Corrected SS Std Error Mean	6.09495	7654 25.3			
$H_0: \mu = 0$	Loca	Basic ation	Statis	stical Measures Variability					
2 LE 2	Mean Median	7.850000 7.000000	Vari	Deviation Lance	2.46880 6.09496				
18 0 0	Mode	7.000000	Rang	je erquartile Range	12.00000		Extreme Ob	servations	
1 1 " " " (g))					Low	est	High	est
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						3	12	12	111
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						3	3	14	115

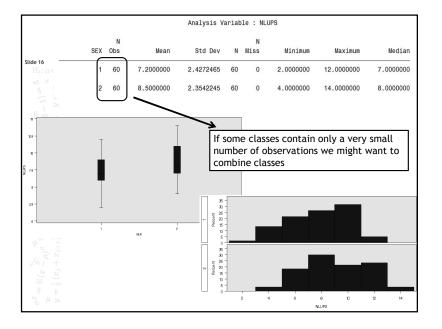


2) Relations explanatory variables and the response variable.

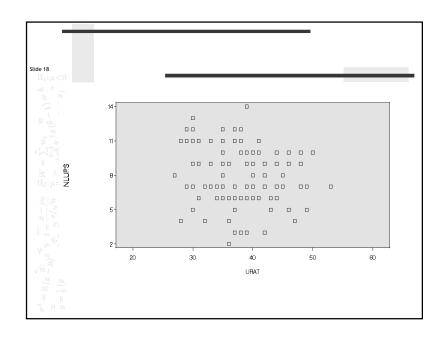
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Get a first, rough idea about the effect of the fixed effect classes.

Get a first clue about the type of relationship between the regressors and the response variables.

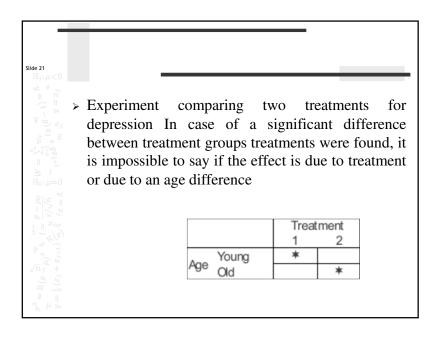


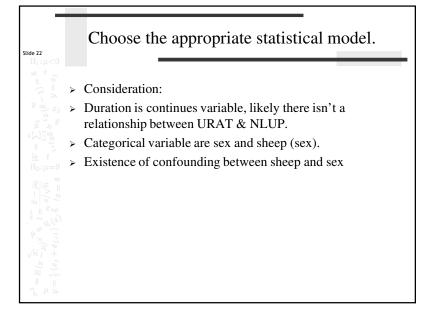
				Analysis Va	ariab	le : NLU	JPS		
lide 17	SHEEP	N Obs	Mean	Std Dev	N	N Miss	Minimum	Maximum	Median
H ₁ :μ<	1	20	4.8000000	1.6415654	20	0	2.0000000	7.0000000	5.0000000
	2	20	9.5000000	1.1920791	20	0	7.0000000	12.0000000	10.0000000
	3	20	7.3000000	1.5927467	20	0	5.0000000	11.0000000	7.0000000
	4	20	7.2500000	1.7733406	20	0	4.0000000	11.0000000	7.0000000
	5	20	7.5000000	1.7917942	20	0	4.0000000	11.0000000	7.0000000
	6	20	10.7500000	1.6819475	20	0	7.0000000	14.0000000	11.0000000
$\begin{aligned} & \theta^2 = B(x-t)^2 & \text{where} & \frac{x_1 - x_2 - y_0}{2} \\ & \pi & \text{where} & \frac{1}{2}(x_j + x_{j+1}) & \text{where} & \frac{x_1 - x_2 - y_0}{2} \\ & y = \frac{1}{2}(x_j + x_{j+1}) & \text{where} & \frac{x_2 - y_0}{2} \end{aligned}$		55 - 10 - 10 - 10 - 10 - 10 - 10 - 10 -	Ī		SHEE				

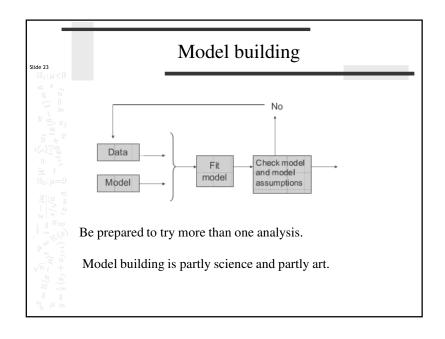


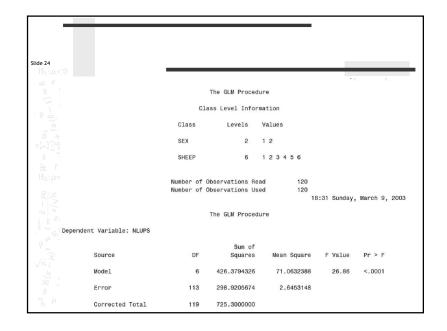
3) Relations among explanatory variables. Explanatory variables might (partly) explain the same variation in the response variable. Confounding: Two variables are confounded if they vary together in such a way that it is impossible to determine which variable is responsible for an observed effect.

	SEX	N Obs	Mean	Std	Dev	N	N Miss	Min	imum	Max	cimum	Median
ide 20 H_1 : μ <	1	60	40.5833333	5.1561	767	60	0	28.000	0000	53.000	00000	40.5000000
e s	2	60	35.6000000	4.7271	305	60	0	27.000	0000	48.000	00000	35.0000000
79 8												
				Analysis	Varia	able :	URAT					
SHE	EP (N Obs	Mean	Std Dev	N	N Miss		Minimum	Max	imum	Me	dian
	1	20	36.8000000	3.8333715	20	0	28.	0000000	43.000	00000	37.000	00000
	2	20	40.7500000	4.3270873	20	0	35.	0000000	50.000	00000	41.000	00000
	3	20	44.2000000	4.5026308	20	0	37.	0000000	53.000	00000	44.000	00000
	4	20	38.1500000	5.0186494	20	0	30.	0000000	48.000	00000	39.000	00000
	5	20	34.8000000	4.3115512	20	0	27.	0000000	46.000	00000	35.000	00000
	6	20	33.8500000	3.8563004	20	0	28.	0000000	40.000	00000	33.500	00000

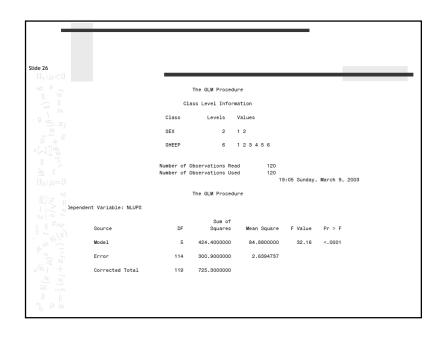


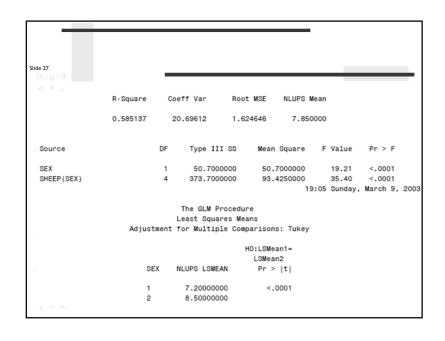


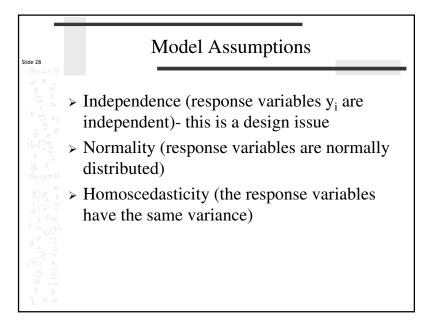


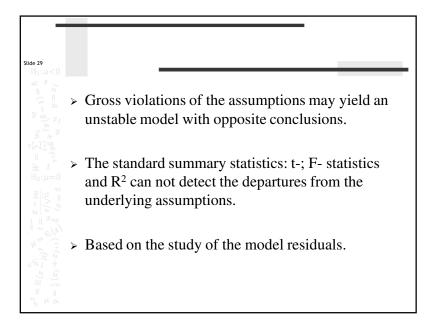


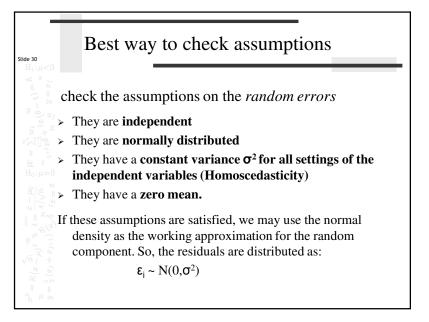
	R-Square	Co	eff Var	Roc	t MSE	NLUPS	Mean			
	0.587866	2	0.71901	1.6	26442	7.85	0000			
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URAT		1	1.97	794326	1.5	9794326		0.75	0.3889	
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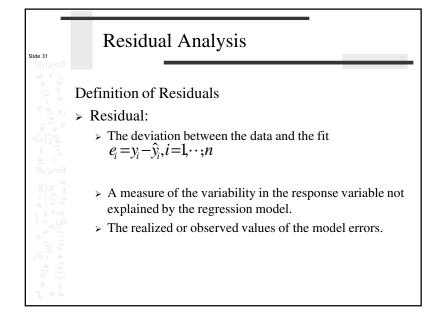


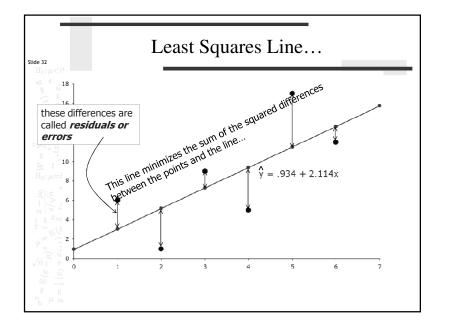








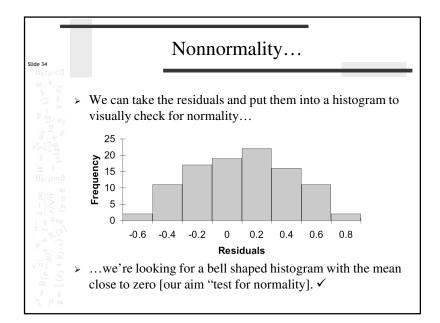




Normality

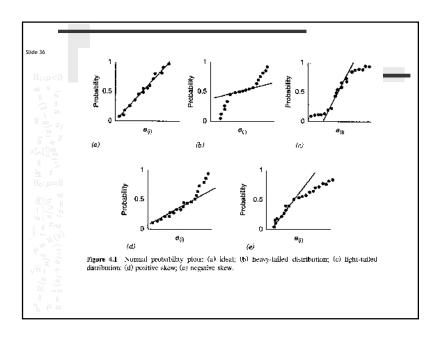
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- > The random errors can be regarded as a random sample from a $N(0,\sigma^2)$ distribution, so we can check this assumption by checking whether the residuals might have come from a normal distribution.
- > We should look at the standardized residuals
- > Options for looking at distribution:
 - > Histogram, Stem and leaf plot, Normal plot of residuals



Normal Plot of Residuals

- A normal probability plot is found by plotting the residuals of the observed sample against the corresponding residuals of a standard normal distribution N(0,1)
 - > If the plot shows a **straight line**, it is reasonable to assume that the observed sample comes from a normal distribution.
 - > If the points deviate a lot from a straight line, there is evidence against the assumption that the random errors are an independent sample from a normal distribution.



Plotting Residuals

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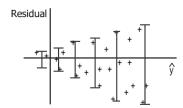
- > To check for **Homoscedasticity** (constant variance):
 - > Produce a scatter plot of the standardized residuals against the fitted values.
 - > Produce a scatter plot of the standardized residuals against each of the independent variables.
- > If assumptions are satisfied, residuals should vary randomly around zero and the spread of the residuals should be about the same throughout the plot (no systematic patterns.)

Homoscedasticity is probably violated if...

- ➤ The residuals seem to increase or decrease in average magnitude with the fitted values, it is an indication that the variance of the residuals is not constant.
- > The points in the plot lie on a curve around zero, rather than fluctuating randomly.
- > A few points in the plot lie a long way from the rest of the points.

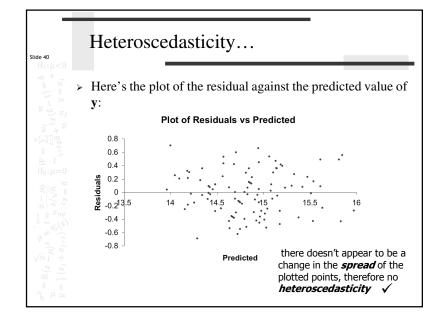
Heteroscedasticity...

> When the requirement of a constant variance is violated, we have a condition of *heteroscedasticity*.

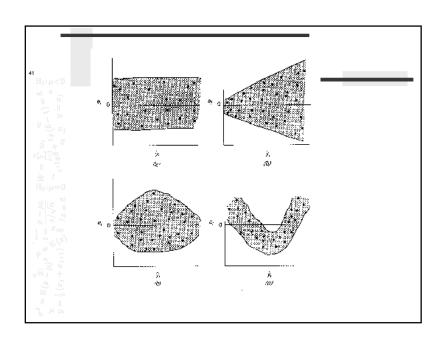


The spread increases with ŷ

> We can diagnose heteroscedasticity by plotting the residual against the predicted y.



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Plot of Residuals against the Fitted Values:

From Fig:

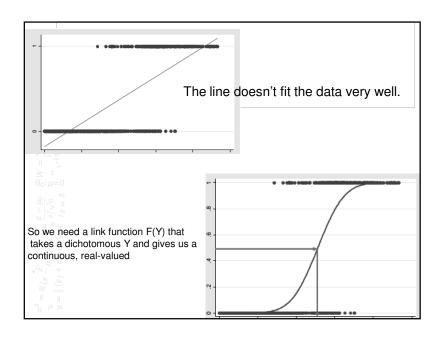
- 1. Fig a: Satisfactory
- 2. Fig b: Variance is an increase function of y
- 3. Fig c: Often occurs when y is a proportion between 0 and 1.
- 4. Fig d: Indicate nonlinearity.
- > For 2. and 3., use suitable transformations to either the regressor or the response variable or use the method of weighted LS.
- For 4., except the above two methods, the other regressors are needed in the model.

Nonlinear Estimation

- > Until now Y, the dependent variable, was continuous.
- > Independent variables could be dichotomous (dummy variables).
- > We'll start our exploration of non-linear estimation with dichotomous Y vars.
- > These arise in many science problems:
 - Survival (0 and 1)
 - > Calving ease (1, 2, 3, 4)

Nonlinear models

In these examples, the dependent variables are not continuous, and classical regression or analysis of variance may not be appropriate because assumptions such as homogeneity of variance and linearity are often not satisfied. Further, these variables do not have normal distributions and *F or t tests are* not valid.



The Structure of Generalized Linear Models

 H_1

Generalized linear models are models in which independent variables explain a function of the mean of a dependent variable.

This is in contrast to classical linear models in which the independent variables explain the dependent variable or its mean directly. Which function is applicable depends on the distribution of the dependent variable.

A generalized linear model consists of three components:

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- 1. A random component, specifying the conditional distribution of the response variable, y_i , given the explanatory variables.
- Traditionally, the random component is a member of an "exponential family" (the normal (Gaussian), binomial, Poisson, gamma, or inverse-Gaussian families of distributions) but generalized linear models have been extended beyond the exponential families.

> generalized linear models (GLMs) extend the range of application of linear statistical models by accommodating response variables with non-normal conditional distributions.

Except for the error, the right-hand side of a generalized linear model is essentially the same as for a linear model.

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Normal distribution—a family of distributions, each member of which can be defined by the mean and variance—many physical phenomena can be approximated well by the normal distribution.

Binomial distribution—probability distribution of # of successes in a sequence of Bermoulli trials (where outcomes fall into one of two categories—i.e., "occurred" and "did not occur". Note that in large samples, if the dependent variable is not too skewed, then the normal distribution approximates the binomial distribution.

2. A linear function of the regressors (<u>linear predictor</u>)

$$\eta_i = \alpha + \beta_1 X_{i1} + \dots + \beta_k X_{ik} = \mathbf{x}_i' \boldsymbol{\beta}$$

on which the expected value μ_i of y depends.

The X's may include quantitative predictors, but they may also include transformations of predictors, polynomial terms, contrasts generated from factors, interaction regressors, etc.

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Poisson Distribution

- expresses the probability of a # of events occurring in a fixed period of time, if the events occur with a known average rate, and independently of the time since the last event.
- Poisson distributions are often used in modeling count data. Poisson random variables take on nonnegative integer values, 0, 1, 2,

3. An invertible link function, $g(\mu_i) = \eta_i$

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which transforms the expectation of the response to the linear predictor.

• The inverse of the link function is sometimes called the *mean* function:

$$g^{-1}(\eta_i) = \mu_i$$

Standard link functions and their inverses:									
Link	$\eta_i = g(\mu_i)$	$\mu_i = g^{-1}(\eta_i)$							
identity	μ_i	η_i							
log	$\log_e \mu_i$	e^{η_i}							
inverse	$\log_e \mu_i \\ \mu_i^{-1}$	η_i^{-1}							
inverse-square	μ_i^{-2}	$\eta_i^{-1/2}$							
square-root	$\sqrt{\mu_i}$	$\eta_i^{-1} \\ \eta_i^{-1/2} \\ \eta_i^2$							
logit	$\log_e \frac{\mu_i}{1 - \mu_i} \Phi^{-1}(\mu_i)$	$\frac{1}{1+e^{-\eta_i}}$							
probit	$\Phi^{-1}(\mu_i)^{'}$	$\Phi(\eta_i)$							
log-log	$-\log_e[-\log_e(\mu_i)]$	$\exp[-\exp(-\eta_i)]$							
complementary log-log									

The logit, probit, and complementary-log-log links are for binomial data, where Y_i represents the observed proportion and μ_i the expected proportion of "successes" in n_i binomial trials — that is, μ_i is the probability of a success.